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Abstract: This work aims to propose a method enabling the evaluation of wind turbine blade damage and fatigue related to a 1 Hz wind speed signal applied to a large period and based on standard 10-min SCADA data. Previous studies emphasize the need for sampling with a 1 Hz frequency when carrying out blade damage computation. However, such methods cannot be applied to evaluate the damage for a long period of time due to the complexity of computation and data availability. Moreover, 1 Hz SCADA data are not commonly used in the wind farm industry because they require a large data storage capacity. Applying such an approach, which is based on a 1 Hz wind speed signal, to current wind farms is not a trivial pursuit. The present work investigates the possibility of overcoming the preceding issues by estimating the equivalent 1 Hz wind speed damage over a 10-min period characterized by SCADA data in terms of measured mean wind speed and turbulence intensity. Then, a discussion is carried out regarding a method to estimate the uncertainty of the simulation, in a bid to come up with a tool facilitating decision-making by the operator. A statistical analysis of the damage assessed for different wind turbines is thus proposed to determine which one has sustained the most damage. Finally, the probability of reaching a critical damage level over time is then proposed, allowing the operator to optimize the operating and maintenance schedule.

Keywords: predictive maintenance; wind turbine blade; rainflow counting; damage estimation; composite materials

1. Introduction

The share taken up by wind energy in worldwide electricity production is expected to grow from its current 5% to 45% by 2050 to support the ever-growing need for energy [1]. The levelized cost of energy (LCOE) is one of the key drivers that will undergird this production growth. Operation and maintenance (O&M) optimization is among the main elements that must be in place to ensure a reduction in the LCOE, and should be a major factor behind the expected 30% decrease in wind turbine (WT) energy production cost from 2020 to 2050. Wind turbine blades (WTB) represent a key component of a WT fatigue purpose, firstly because their failure rate is one of the highest among the other components (0.13/year, similar to the failure rate observed for the gearbox, the transformer, or the tower [2,3]). Secondly, their replacement or repair cost is very expensive, because they involve rope access or mobilizing a crane [4,5].

The predictive maintenance of WTBs to minimize their associated O&M costs or assess the possibility of WT life extension is a major purpose of current research efforts. Predictive maintenance relies on smart planning to avoid expensive corrective action and high repair costs linked to reactive maintenance. Two main families of predictive maintenance already exist [6]. The first one regroups the data-driven models. Among them, a predictive maintenance model based on an exponential expression of the WTB damage behavior can be found [7]. Another model relies on the Bayesian dynamic network; it discretizes the WTB damage into levels of damage, and the possibility of going from



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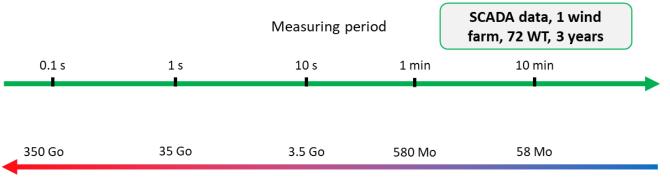
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Copyright: © 2023 by the authors. Licensee MDPI, Basel, Switzerland. This article is an open access article distributed under the terms and conditions of the Creative Commons Attribution (CC BY) license (https:// creativecommons.org/licenses/by/ 4.0/). one damage level to the next is given by a probability law. The data-driven model can provide a damage estimation with a small computing capacity [6,7]. The drawback is that it is challenging for these models to find parameters to achieve a reliable remaining useful life (RUL) evaluation.

The second family of predictive maintenance relies on physical models such as that of Eder and Chen (2020) [8]. There are different physical methods enabling to estimate the WTB RUL. The most used method is based on the Miner's rule and it is easy to operate [9–20]. Other models exist, but they are less employed due to their inherent use limits such as the method relying on the Paris-Erdogan or Walker's elastic crack propagation law [8,21] or the stiffness degradation fatigue theories about composite materials [11]. The physical models are known to allow accurate estimations of damage behavior. However, their associated computations are extremely time consuming when considering the complete lifetime of a WT (typically 25 to 30 years). Moreover, as laid out by Jang et al. [13], a reliable WTB damage evaluation requires a 1 Hz wind speed (WS) sampling frequency because WTBs are sensitive to WS fluctuations at this frequency. As a result, because 1 Hz WS data are very hefty, and because fatigue computation via physical damage models is time consuming, the WTB damage cannot be evaluated for a large period of time [13]. Then, the industry norm is to work with 10-min aggregated signals (average, min, max, standard deviation), as recommended by the IEC standard 61400-12-1 [22]. The 10-min period has been proven to provide enough information to evaluate the energetic aspects of the WT [20]. However, as mentioned above, WTB fatigue assessment requires data with higher frequencies, which are not always archived in the SCADA systems. Figure 1 presents the differences between various aggregation intervals in terms of data volume. This situation forces to design a fatigue damage computation tool working with the 10-min SCADA data in order to be applicable to as many wind farms as possible.



Data

Figure 1. Schema showing the relation between data weight and the measuring period for a wind farm composed of 72 WT for a period of 3 years.

The present study intends to achieve this goal to come up with a way to estimate blade damage regarding 10-min SCADA data. The presented model starts by computing the damage induced by the fluctuation of the 10-min mean WS stored in the SCADA data using the well-known Miner's rule. This damage will be called low cycle fatigue (LCF) in this study. Then, the damage induced by WS fluctuations within each 10-min SCADA data period is investigated. To achieve this, a 1 Hz stochastic WS signal is numerically generated via a turbulence model based on the Kaimal spectrum [23,24], in correlation with the previous 10-min SCADA data. Then, the corresponding damage is again computed via the Miner's rule. This damage will be called high cycle fatigue (HCF) in this study. Finally, by combining the LCF and the HCF, it is expected to obtain an overall relative WTB fatigue damage evaluation. Finally, applying this method to an entire wind farm enables to highlight which WT is the most damaged and allow the wind farm operator to optimize his maintenance operations. The main breakthrough here is the possibility to achieve for the

first time a damage evaluation based on a physical model, considering a 1 Hz WS signal extending through the entire WT lifetime by lowering many of the computation needs.

This study is divided into four main parts. The first section deals with the data and the numeric tools at our disposal, followed by a presentation of the hypothesis of the model developed. The second section presents the LCF damage estimation methodology based on 10-min WS SCADA signals. The third section shows the HCF damage estimation methodology, based on 1 Hz simulated WS signals. The HCF damage estimation aims to be added to the LCF evaluation based on 10-min SCADA data because the fatigue is a cumulative phenomenon. Then, results are analyzed and discussed in the fourth section. Finally, the conclusion proposes a global overview of the breakthroughs brought by this study and suggests other future leads to improve the results already obtained with the present method.

2. Resources and Hypothesis

2.1. Resources

To carry out this study, we have access to 10-min aggregated signals from SCADA data (specifically, a 10-min mean WS history) of a wind farm composed of 5 MW WT from February 2017 to May 2020. Then, Matlab[®] programming language and FAST aeroelastic models [25] were used to estimate the aerodynamic loads leading to stress variations, and consequently, damage due to WS fluctuations. However, to estimate the inner stress in the WTB, a detailed numeric model of the WTB should be used. Because the wind turbine model installed on the studied windfarm is unknown for confidentiality issues, a 5 MW WT numeric model from the NREL library (open access) was used as reference [26,27]. This numeric model was chosen as it is the most common and most studied model in the literature. In this context, it is assumed that the evaluated fatigue damage on the numeric wind turbines will differ from the real wind turbines operating in this wind farm, but the ranking of the most damaged wind turbine is expected to remain the same. Hence, the damage computed in this project is relative and not absolute.

2.2. Considered Environmental Effects and Hypothesis

WTB fatigue is caused by different environmental factors, such as rain erosion [28], the gravity effect [29], and temperature variations, all of which can also affect the material fatigue strength [30] at different locations. The blades are submitted to two mains bending moments, the flapwise bending and the edgewise bending [20,22,31,32] (Figure 2). Because they are locations on the WTB depending almost only on flapwise bending (like the adhesive bond line in the trailing edge [8]) or on edgewise bending, it is possible to consider only one of these types of bending in such locations for fatigue purpose [8,12,22,31]. Depending on the localization on the blade root, the blade root section can be at the same time only subjected to flapwise bending at the blade root is much higher than the edgewise one [12,32]. Moreover, the flapwise bending is provoked by the wind while the edgewise bending is mainly caused by the weight of the blade [31–33]. So, the wind speed variations can be assumed to be the major factor influencing the WTB fatigue as already suggested in the scientific literature [19,32]. Thus, for simplicity, we will focus only on this aspect in the rest of this paper.

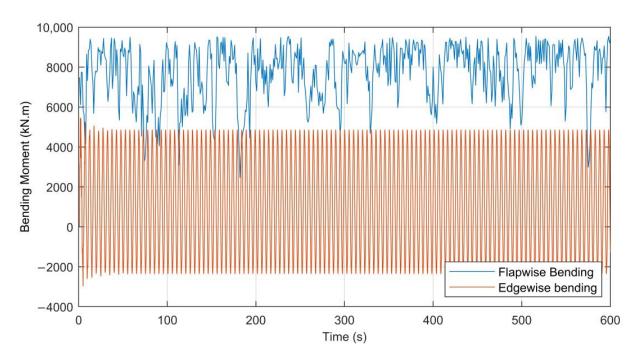


Figure 2. Flapwise and edgewise bending moments for a mean wind speed of 11 m·s⁻¹ and a TI = 20%.

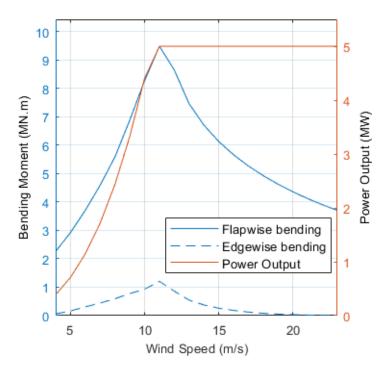
2.3. Hypothesis

The damage is considered at the blade root section for two main reasons. Firstly, because it is expected to be the most sensitive part to fatigue issues [31,31,32,34], and secondly, because it generally has a circular section no matter the wind turbine model and the rest of the blade structural design [8,16,31–33], which is not publicly shared by the wind turbine OEM [33]. At the blade root, only the diameter and the skin thickness depends of the global length of the blade [26,33,35], facilitating the extrapolation of a conceivable root structure design from basic information from the numeric WTB model. The damage is due to variations in the stress within the part, which is correlated with flapwise bending and edgewise bending. Considering a zero pitch, the flapwise bending corresponds to the out-rotor plane direction while the edgewise bending is associated with the in-rotor plane direction. However, according to estimations carried out with FAST and a 5 MW wind turbine blade from the NREL library, of the two, flapwise bending would seem to be more sensitive to WS fluctuations (see Figure 3), which is why, in the present study, we focus on the stress resulting from it. Regarding the simulated 1 Hz WS signal, the simulated wind is also considered to be blowing in the rotor axis like the previous one, but it is generated stochastically using the Kaimal spectrum proposed in the FAST TurbSim module [24]. The Kaimal spectrum is often used in the wind turbine fatigue field to generate a turbulent wind field [36,37] because it has been designed for a homogeneous and flat onshore site [38]. It best describes the turbulence wind field within the atmospheric boundary layer, where the earth's surface has a strong influence on the atmosphere [39]. This is why it is a recommended model for the wind turbine industry, according to standard IEC 61,400 [20]. Finally, because of the cumulative nature of the damage, the overall WTB damage is assumed to be the sum of the HCF and LCF damage and other factors, defined as follows:

$$D_{Tot}(t) = D_{LCF}(t) + D_{HCF}(t) + D_{SD/SU}(t) + D_{Events}(t) + D_{t_0}$$
(1)

where D_{Tot} is the overall WTB root damage at time t, D_{LCF} is the damage due to LCF, D_{HCF} is the damage due to HCF, $D_{SD/SU}$ is the damage induced by transient regimes (shut-down and start-up of the WT), D_{Events} is the damage caused by extreme environmental conditions such as storm-inducing wind velocities higher than the cut-out WS of the wind turbine (in

our case, 25 m·s⁻¹), damage due to lightening, etc., and finally, D_{t_0} is the initial damage induced by manufacturing at time t_0 . Here, D_{Events} is not considered because it relies on complex mechanisms like resonance issues or sudden material failures not related to fatigue behavior, according to Chou et al. [40]. D_{t_0} is also not considered for reasons of simplification because it relies on defects not depending on fatigue behavior and that are harsh to assess, even though they can have a strong effect on WT strength [16,41,42]. In addition, $D_{SD/SU}$ is also not considered here because it requires a finer analysis of the startup and shut-down procedures used by the wind farm operator to assess the corresponding damage [12,43]. In the present work, only D_{LCF} and D_{HCF} are considered because they refer to the WTB fatigue behavior. This study introduces for the first time an estimation of the HCF based on 10-min aggregated SCADA data commonly used in the wind farm industry, enabling to evaluate the WTB fatigue damage for a long period of time covering the entire life span of the WT. Hence, the overall damage is summarized in Equation (2):



$$D_{Tot}(t) \approx D_{LCF}(t) + D_{HCF}(t)$$
⁽²⁾

Figure 3. Mean bending moments and output power as a function of the wind speed.

3. LCF Damage Assessment

3.1. Assessment of Stress

Using FAST software and the geometric properties of a 5 MW WT model from the NREL library, the flapwise bending moment (M_{flap}) at the blade root could be estimated according to the WS (see Figure 3). Following this, and knowing the flapwise bending moment and the geometry of the WTB, it was then possible to estimate the stress history according to the mean WS history (seen at the blade root thanks to Equation (3) (see Figure 4):

$$\sigma_{flap} = \frac{M_{flap}c}{I} \tag{3}$$

with σ_{flap} being the resulting stress [Pa]. *c* is the maximum distance from the neutral axis, which corresponds approximately to the chord line for a WTB in bending. So, *c* is nearly equal to half of the airfoil thickness [m] at the root [31,33]. *I* is the moment of inertia of the WTB root section [m⁴]. To obtain *I*, the skin thickness of the blade at the root section t_{root} [m] must be known. However, this information is not provided with the numerical WTB model used in this study. Furthermore, the WTB root thickness for a 5 MW WT

varies strongly (from 50 to 80 mm) depending on the sources [44–46], making it difficult to obtain a reliable extrapolation. So, it has been arbitrarily chosen to approximate t_{root} via the following empirical law [33]:

$$t_{root} \approx 0.08 \sqrt{\frac{R}{40}}$$
 (4)

where *R* [m] is the rotor radius (here, R = 64 m for the 5 MW FAST WT model).

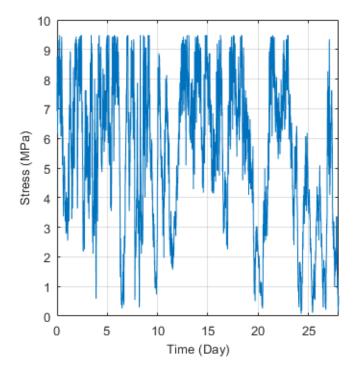


Figure 4. Estimated stress history for a period of 4 weeks for a single 5 MW wind turbine.

The next step is to carry out the Rainflow Counting algorithm (RFC) as defined in [47] according to the standards [14,20], to have the stress cycle characterization regarding the stress history.

$$[\Delta\sigma_i, n_i] = \operatorname{RFC}(u(t), |\sigma|, \sigma_u) \tag{5}$$

Here, $\Delta \sigma_i$ [MPa] is the stress range amplitude of the cycles, n_i corresponds to the number of cycles according to the cycle amplitude $\Delta \sigma_i$, *i* refers to the *i*-th stress cycle. Then, the WTB damage can be estimated as presented in the next section.

3.2. Damage Evaluation Based on 10-min SCADA Data

Many studies rely on stress variation to carry out WTB damage evaluation [9–11,13]. However, according to [14], it is recommended to work with the strain variation rather than stress variation in order to evaluate the damage level in composite materials due to the fatigue phenomenon. One reason for this is that the strain remains the same between the plies composing the laminate when a force is applied to the latter, while it is not the case with the stress (see Figure 5).

The guide proposed by Germanischer Lloyd, or DNV GL, since 2013 [14] lays out an approach based on the strain and the Goodman diagram of the considered laminate to assess the damage behavior due to fatigue. For a certain *i*-th strain cycle characteristic, the corresponding N_i can be known via Equation (6), with the parameters explained in the nomenclature:

$$N_{i} = \left[\frac{R_{k,t} + |R_{k,c}| - |2 \gamma_{Ma} S_{k,M} - R_{k,t} + |R_{k,c}||}{2 (\gamma_{Mb}/C_{1b}) S_{k,A}}\right]^{m}$$
(6)

According to [14], it is expected that

$$\gamma_{Mb} / C_{1b} = \gamma_{M0} C_{2b} C_{3b} C_{4b} C_{5b} \tag{7}$$

Here, $S_{k,M}$ and $S_{k,A}$ can be derived from the previous RFC of the stress. Knowing the stacking of layers within the blade root section, the corresponding Young's modulus of the material at the WTB root can be obtained [48]. After which, once the Young's modulus is evaluated, the RFC of the stress can be converted into the RFC of the strain via the Hooke's law, providing $S_{k,M}$ and $S_{k,A}$ for each strain cycle. Then, starting from Equation (5), the RFC of the strain allows to estimate the following:

$$[S_{k,A}, n_i] = \operatorname{RFC}(u(t), S_{k,M}, S_u)$$
(8)

where S_u is the maximum strain to rupture of the weakest ply composing the laminate.

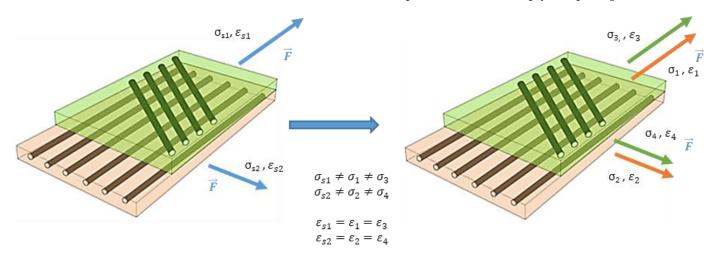


Figure 5. Schema showing the relationship between plies strains within a laminate.

Finally, as recommended by the standards [14,20], via the Miner's rule (Equation (9)) with N_i provided by Equation (6) and n_i given by the RFC of the strain, an estimation of the WTB's LCF damage $d_{LCF,i}$ for the corresponding *i*-th cycle can be computed:

$$d_{LCF,i} = \frac{n_i}{N_i} \tag{9}$$

Then, the global LCF damage D_{LCF} is computed as the sum of $d_{LCF,i}$ encountered within the period of study. The global methodology is summarized in Figure 6:

$$D_{LCF} = \sum_{i} d_{LCF,i} \tag{10}$$

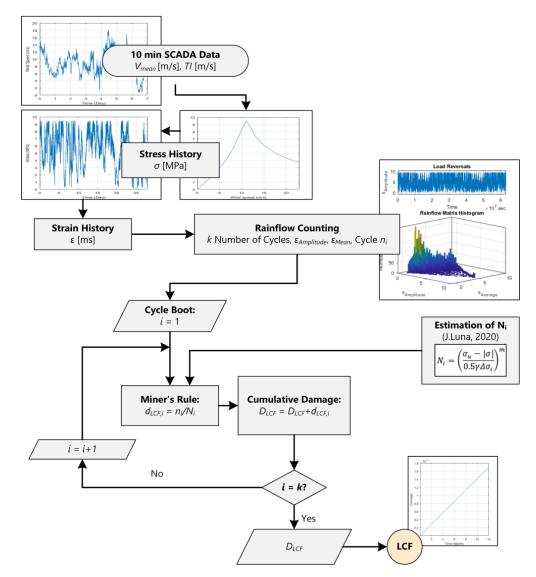


Figure 6. Flowchart showing the process leading to the estimation of the LCF damage from SCADA data.

4. HCF Damage Evaluation

According to [13], it is necessary to work with an approximately 1 Hz WS signal to ensure a reliable damage estimation. WS signal histories with high sampling rates are uncommon, and where available, their processing is heavily computing resource-intensive because of the sheer volume of data involved (≈ 600 times more than 10-min SCADA data, as shown in Figure 1). To overcome these issues, the approach presented herein consists in estimating the damage due to a 1 Hz WS signal for a 10-min period parametrized with a mean WS and turbulence intensity (*T1*) defined as follows [13,49]:

$$TI = \frac{\sigma_V}{\overline{V}} \tag{11}$$

Here, σ_V is the standard deviation of the measured WS over a 10-min period and \overline{V} [m·s⁻¹] is the measured mean WS within this period.

TurbSim FAST's module is used here to generate the required WS signals [24]. Series of WS signals are generated for all the wind characteristics (in terms on mean WS and *TI*) that the WT can meet in normal operating conditions as defined by the norm IEC-61400-1 [20]. So, each series of WS signals is simulated regarding a specific mean WS and *TI* from a range of values starting from the cut-in WS to the cut-out WS and a *TI* of 1% to 50% as advised

by [20]. The model runs with the Kaimal spectrum to generate a turbulent wind flow as recommended by the standards [14,20]. The Kaimal spectrum is used in the wind turbine industry to generate stochastic and turbulent wind flow [50].

Because the WS signals are generated stochastically trying to reflect the wind's behavior in the nature [51], a generated WS signal can differ from another even if they share the same \overline{V} and TI. So, it is expected that the resulting WTB damage from a generated WS signal can also differ from another WS signal, even if those signals have the same parameters— \overline{V} and TI. That is why a series composed of numerous stochastic simulations must be carried out for each \overline{V} and TI, to cover a wide variety of possible signals—and thus, of resulting damage. Each WS signal is simulated at a 1 Hz frequency for a 10-min period with the \overline{V} and TI parameters associated to the WS series that they belong to, as shown in Figure 7. After 100 simulations, the damage distribution tends to maintain a single shape, converging to the same distribution values. Hence, it has been chosen to fix at 100 the number of WS signals within each WS series. Then, for each simulation (or WS signal), the equivalent HCF damage d_{HCF} is assessed using the methodology presented in Section 3.2. Because each simulation corresponds to a proper d_{HCF} , the results can be expressed under the form of a cumulative distribution function (CDF) of d_{HCF} for each WS series \overline{V} and parameter (see Figure 8).

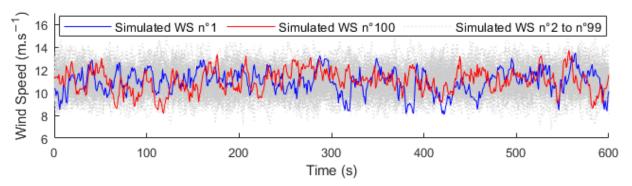


Figure 7. Simulation of 100 stochastic wind speed signals with $\overline{V} = 11 \text{ m} \cdot \text{s}^{-1}$ and TI = 10% for a period of 10 min.

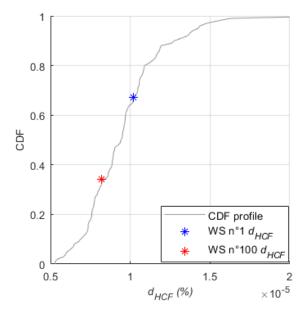


Figure 8. Estimated damage CDF for a WS series with the following parameters: $\overline{V} = 11 \text{ m} \cdot \text{s}^{-1}$ and TI = 10% over a period of 10 min.

Then, for each 10-min period of the SCADA data history, the associated \overline{V} and the *TI* are identified and the WS series damage CDF with the corresponding parameters is

selected. Next, the equivalent $d_{HCF,t}$ for this 10-min period is chosen according to the cumulative distribution value (CDV) X_t .

$$d_{HCF,t} = F^{-1}(X_t)$$
(12)

where X_t of the selected CDF is chosen according to the damage percentile considered, with the time steps t and F being the functions describing the damage CDF. Finally, by cumulating the selected $d_{HCF,t}$ for the entire 10-min mean WS history, the overall WTB damage D_{HCF} can be calculated:

$$D_{HCF} = \sum_{t} d_{HCF,t} \tag{13}$$

Hence, D_{HCF} can be computed for a long period (1 year in this case) and the probability distribution function (PDF) of D_{HCF} can be extrapolated by varying the value of X_t . The D_{HCF} assessment methodology used is summarized in Figure 9.

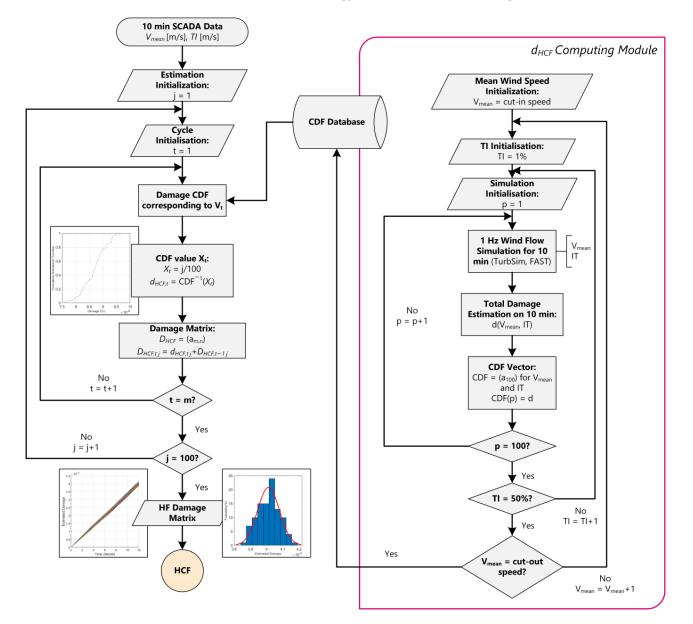


Figure 9. Flowchart showing the process leading to the estimation of the HCF damage from the SCADA data.

5. Results and Discussion

5.1. Damage Estimation

Regarding Equation (2), the global WTB damage $D_{Tot}(t)$ can be computed as the sum of $D_{LCF}(t)$ and $D_{HCF}(t)$. To evaluate the WTB damage for several years, it has been chosen to concatenate the 1-year WS history by the number of years required to have an approximation of the entire life WS history. However, from the results obtained, it appears that $D_{HCF}(t)$ is much higher than $D_{LCF}(t)$ (see Table 1). These results can be explained by the fact that the sampling frequency of the signal used for the fatigue estimation strongly influences the WTB damage estimation, as described by [52]. According to these results, $D_{Tot}(t)$ could be approximated as equal to D_{HCF} to simplify the presented WTB damage estimation process. Thus, the following relation can be assumed, in the case where only the operation running regime is considered:

$$D_{Tot} \approx D_{HCF}$$
 (14)

Table 1. Table showing the difference between LCF and HCF (TI = 1%) damage estimations for different lengths of the study period.

| Period of Study | $D_{LCF}(t)$ | Mean D_{HCF} (t) | $D_{HCF}(t)/D_{LCF}(t)$ |
|-----------------|-----------------------|----------------------|-------------------------|
| 1 year | $7.94 	imes 10^{-5}$ | 4.02 | $5.06	imes10^4$ |
| 20 years | 1.56×10^{-3} | 7.12×10^{1} | $4.56 	imes 10^4$ |

Based on the hypothesis presented in Section 2.3, leading to Equation (2), it was decided to consider only the WTB damage due to the operation running regime and a relatively simple geometry at the blade root. In Section 5.3, a discussion about how to increase the reliability of the results is presented.

5.2. Impact of TI and \overline{V} on HCF Damage

According to the results presented in Figure 10, it appears that *V* has a strong impact on d_{HCF} . The computed d_{HCF} reaches its maximum at WS = 11 m·s⁻¹, corresponding to the moment where the WT nominal power and maximum bending moment are met. However, such wide differences can call into question the need to consider any other WS than 11 m·s⁻¹. The *TI* is another parameter influencing d_{HCF} , albeit to a lesser extent. Based on the results of Figure 11, for a WS = 11 m·s⁻¹, d_{HCF} is increased by 30%, with *TI* going from 1% to 5%, and by 1320%, with a *TI* going from 1% to 20%. This result is explained by the fact that with a growing *TI*, the amplitude of the bending cycles, and thus of the strain cycles, increases, leading to an increase in d_{HCF} . Concerning the evaluation of D_{Tot} , a *TI* increase from 10% to 12% represents a damage increase of 50% with D_{Tot} going from 0.04% to 0.06%, as shown in Figures 12 and 13, after 1 year.

5.3. Study Case

This damage model needs to be calibrated despite the good results presented here, for several reasons. Firstly, the thickness of the blade root section was estimated via Equation (4), but uncertainties about the real blade root section thickness persist. Secondly, the layer stack of the material of the blade root section can differ between WTB models [28]. However, this damage model can already be used as a tool to rank WT within the same park according to the evaluated fatigue damage considering the 10-min mean WS SCADA data. In our study case, D_{Tot} was computed for 11 WT of the same wind farm for a 20-year period (see Figure 14). This result can lead to the wind farm operator adopting its O&M schedule and budget accordingly by focusing on WT n°8 (which is assessed as the most damaged WT) in this example.

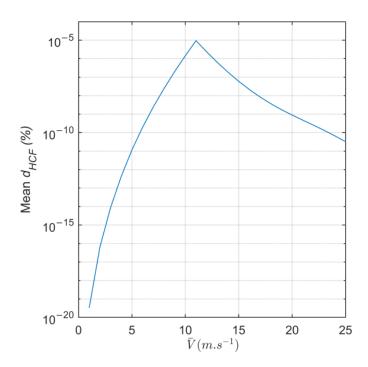


Figure 10. Mean WTB damage d_{HCF} regarding a generated 1 Hz wind speed signal for a 10-min period as function of the \overline{V} with a fixed TI = 10%.

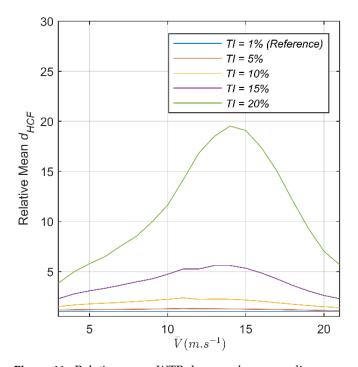


Figure 11. Relative mean WTB damage d_{HCF} regarding a generated 1 Hz wind speed signal for a 10-min period as a function of the \overline{V} for different *TI*, taking the mean d_{HCF} for *TI* = 1% as reference.

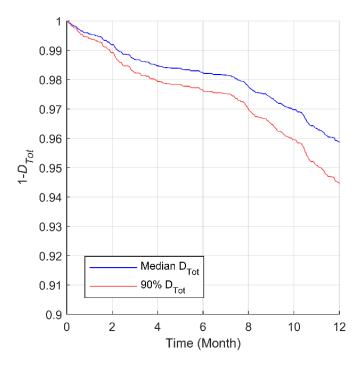


Figure 12. Graphic of $1 - D_{Tot}$ for 1 WT imposing TI = 10% for a 1-year period. In blue, the median D_{Tot} , computed with the 50th percentile of D_{HCF} . In red, 90% D_{Tot} , computed with the 90th percentile of D_{HCF} .

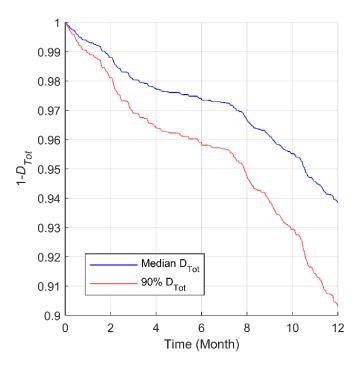


Figure 13. Graphic of $1 - D_{Tot}$ for 1 WT imposing TI = 12% for a 1-year period. In blue, the median D_{Tot} , computed with the 50th percentile of D_{HCF} . In red, 90% D_{Tot} , computed with the 90th percentile of D_{HCF} .

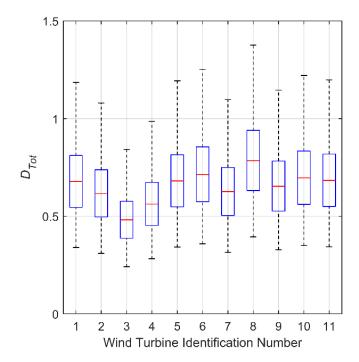


Figure 14. Boxplot of WTB damage *D*_{Tot} for 11 WT within a same park after a 10-year period.

Then, once this model is calibrated, more specific results could be extracted. As an example, taking WT n°8 mentioned above, the D_{Tot} profiles could be computed (see Figure 15). Take note that the oscillation of D_{Tot} is due the season impact, the distribution of the wind flow parameters changing depending on the season.

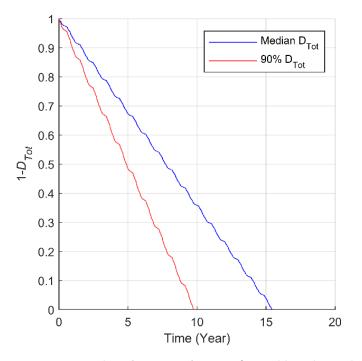


Figure 15. Graphic of $1 - D_{Tot}$ for WT n°8. In blue, the median D_{Tot} , computed with the 50th percentile of D_{HCF} . In red, 90% D_{Tot} , computed with the 90th percentile of D_{HCF} .

The damage presented here is only relative. To have an absolute damage evaluating tool, in addition to the calibration of the damage model, other factors influencing the damage behavior must be considered, notably the impact of the running regime on the WTB damage. In the literature, it appears that the current damage models only focus on

a specific running regime [7–13,15,29,43,53,54]. However, according to them, each running regime does matter in the WTB damage evaluation field. So, as a next step, to improve the damage calculation, the future damage model must take into account other operating regimes influencing D_{Tot} as expressed in Equation (1). This means that the impact of the transient regimes on D_{Tot} must be investigated to obtain a more reliable computation of D_{Tot} . Then, because this tool is developed to help the windfarm operator taking O&M decisions, the next damage model should consider the impact of these operations on the WTB damage level as explained by [6]. Ultimately, because WTs are operated for a long period (around 20 years), it would be interesting to investigate the impact of the climate change on the WTB damage. As explained by [55], climate change can have an important effect on WT performance, and so, on their fatigue damage.

6. Conclusions

In this paper, a method allowing to evaluate WTB high cycle fatigue damage considering 10-min SCADA data is proposed. Firstly, a WTB damage assessment based on 10-min SCADA data and considering the equivalent damage due to a 1 Hz fluctuating WS signals, based on rainflow counting and Palmgren–Miner's rule was put in place. The LCF damage and the HCF damage were separated. The equivalent WTB damages for a 10-min period with a 1 Hz stochastic wind under different environmental parameters were assessed and stored in the form of a damage CDF database. Then, by cumulating the estimated WTB damage CDF for each 10-min SCADA data period, the HCF damage for a long period of time could be computed for the first time. Next, the CDV X_i was selected in terms of the damage percentile of interest to the operator. These different steps enable to have a PDF of the calculated HCF damage, thus providing wind farm operators a more complete decision-making tool regarding their maintenance strategy. After comparing the HCF damage with the LCF damage, the LCF damage appeared to be negligible as compared to that for the HCF, leading to the assumption that the global WTB damage is effectively equal to the latter when only operation running conditions are considered.

Secondly, the WTB damage assessed while taking only operation running conditions into account must also consider other factors, such as transient regimes and extreme environmental conditions, because these can influence the damage behavior of the WTB. Moreover, the model must be calibrated because assumptions will have been made regarding the blade root thickness or the material properties, which could lead to uncertainties about the computed effective damage. The next step will therefore consist in carrying out computations while considering the transient regimes and extreme environmental conditions of WTs and to calibrate the damage model to ensure a more reliable estimation of WTB fatigue damage.

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Nomenclature

- $R_{k,t}$ Characteristic short-term structural member resistance for tension
- $R_{k,c}$ Characteristic short-term structural member resistance for compression
- γ_{Ma} Partial safety factor for material *a*
- γ_{Mb} Partial safety factor for material b
- $S_{k,M}$ Mean value of characteristic cycles
- $S_{k,A}$ Amplitude of characteristic cycles
- *m* Slope parameter of S/N curve
- *C*_{3*a} Vacuum infusion molding effect</sub>*
- *C*_{4*a*} Post-cure polymerization effect
- *C*_{2*b*} Temperature effect
- C_{3b} Non-woven unidirectional fibers effect
- *C*_{4*b*} Post-cure polymerization effect
- C_{5b} Local safety factor at the trailing edge
- *C*_{1*a}</sub> Ageing effect</sub>*
- *C*_{2*a*} Temperature effect

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