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Review Article

Trends and Advances in Urban Logistics Research: A Systematic Literature Review

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It is important to establish appropriate performance indicators so that decision-makers can better determine the best alternatives for sustainable urban freight distribution systems. This literature about urban logistics and routing problems is structured and analyzed through a systematic literature review of a total of 201 papers from 2002 to 2023. Three main axes were considered: problem modeling and solution approaches, multimodal transportation, and indicators to assess the performance and sustainability of the distribution networks. There is a growing trend of research on this topic. Indeed, the paper highlighted the academic interest in the analysis of case studies to test the scenarios and network configurations and proposed solution approaches, as well as the adoption of greener transportation modes. To the best of our knowledge, no previous studies have analyzed the literature from the thematic lines proposed in this review, especially those that refer to performance indicators to assess both the freight distribution networks and the transportation modes considered. Advancing stochastic modeling, expanding case studies to underrepresented regions, integrating AI-driven multimodal logistics, and developing social impact indicators are key research directions to enhance the sustainability and efficiency of urban logistics. This review provides a structured foundation for future research by identifying gaps in the literature and offering a thematic roadmap to advance the study and implement sustainable urban logistics solutions. In addition, its findings can assist decision-makers and logistics planners in evaluating current practices, identifying opportunities for improvement, and supporting the development of more sustainable and efficient distribution strategies.

Keywords: last-mile delivery; performance indicators; routing problems; sustainability; transportation modes; urban logistics

1. Introduction

Over the past few years, the retail sector has experienced notable growth, largely attributed to the circumstances of the pandemic. These conditions prompted an expansion in the sector and led many businesses to transition to e-commerce to sustain their operations [1]. According to Janjevic et al. [2], e-commerce represents 10% of the global retail market and has been the biggest driver of retail growth. In addition, the increase in population worldwide generates greater demand for goods and commodities. E-commerce activities

have a very close relationship with last-mile delivery services, especially for parcel and food delivery. This has triggered an increase in deliveries in urban areas, where the transportation and mobility sector has become essential to cover these demands. This has made delivery operations more complex and expensive.

The use of many vehicles in urban delivery systems has important implications in terms of air pollution, since transportation activities are the source of approximately 25% of carbon dioxide equivalent (CO_2e) emissions, 30% of nitrogen oxide (NOx) emissions, 40% of energy consumption,

and 50% of particle matter [3, 4]. The world's population is exposed to poor air quality that exceeds the World's Health Organization guideline limits, causing cardiovascular and pulmonary diseases [5]. Furthermore, these vehicles generate an increase in traffic congestion, and they saturate parking spaces, making driving difficult when carrying out irregular parking practices that invade public spaces [6]. Limited space in inner-city areas does not allow an expansion of logistics infrastructure. Therefore, in many cities, as a strategy to improve living conditions and make them more sustainable, the access of delivery vehicles to urban areas is restricted [7].

These two trends have led to innovative models of urban distribution [8] and to the promotion and introduction of initiatives to use more environmentally friendly transportation modes with the aim to reduce the negative externalities and to achieve sustainable logistics operations. For instance, governments are promoting regulations to increase the use of electric vehicles (EVs) for urban delivery. In addition, several logistics service providers are incorporating different types of transportation modes (e.g., drones, delivery robots, cargo bikes, and public transport) in their networks [9]. Promising results are found in the literature and in practice regarding the adoption of cleaner energies and alternative transportation modes.

To the best of our knowledge, there are no previous studies that analyze the literature from the thematic lines proposed in this review, especially the one that refers to the indicators that have been used to measure the performance of both the distribution networks and the solution methods applied. As background, there are mainly three reviews that address issues related to the need of making urban distribution networks more sustainable. The work of Patella et al. [10] studied challenges and issues regarding the adoption of green vehicles in urban freight transportation and ecommerce activities and classified the documents into three categories: optimization and scheduling, policy, and sustainability dimensions. Silva et al. [11] classified research works on sustainable urban logistics published between 2016 and 2022 in clusters: supply chain and channels, delivery methods, innovative transportation modes, logistic infrastructures, and emerging business models. The authors organized the solutions that were identified for the last-mile drawbacks into three groups: vehicular, operational, and organizational solutions. Some of the advantages and disadvantages of these solutions were discussed. Golinska-Dawson and Sethanan [12] focused on the emerging solutions in terms of hardware and software applied by logistics service providers that can support the adoption of environmentally friendly (in terms of energy) smart cities. The study classified the solutions in urban freight consolidation or transshipment, customers as service providers (i.e., the use of crowdshipping), and modes of transportation. In contrast to those previous works, the proposed literature about urban logistics and routing problems is structured and analyzed through a systematic literature review. The findings are classified into three main axes: problem modeling and solution approaches, multimodal transportation, and indicators to assess the performance and sustainability of the delivery networks.

The remainder of the paper is organized as follows. Section 2 presents the methodology of the systematic literature review. A descriptive analysis of the selected papers is presented in Section 3. Section 4 presents the most common modeling and solution approaches used in the papers with a technical outline of adopted methodologies, their reference to practice, and a thorough analysis of their properties. Section 5 presents an analysis of the different transportation modes with some of the benefits, advantages, and disadvantages. A detailed description of the indicators used to measure the performance of the distribution networks is given in Section 6. Finally, Section 7 presents the conclusions and outlines opportunities for future research.

2. Research Methodology

This section describes the research methodology. A systematic review involves a detailed analysis of the scientific literature under a planned and carefully executed process, with the purpose of reducing bias through the identification and synthesis of previously published findings on a particular topic, to answer a specific research question [13]. From the academic side, this approach increases methodological rigor; while, for practitioners and managers, it can help to develop a trustworthy knowledge base by consolidating knowledge from a set of studies [14]. We followed the method and steps proposed by [14], whose process begins by defining one or more research questions to define the scope of the review. Our study has the aim of giving answers to the three following questions:

- 1. How are urban parcel delivery problems modeled?
- 2. Which solution methods are employed to deal with urban parcel delivery problems?
- 3. Which are the transportation modes that have been considered in literature?
- 4. Which are the performance indicators applied in the literature to assess the sustainability and efficiency of multimodal urban parcel delivery systems?

Based on these questions, the second stage is to define the search criteria. To locate the set of publications relevant to our purposes, three keywords were used: "Urban logistics," "city logistics," and "routing problems." After testing different combinations of such keywords, the final search string was defined as follows: TITLE-ABS-KEY (urban OR city AND logistics AND "routing problems"), because it contained a more complete list of articles. The database used in this search was Scopus since it is one of the major databases that provide access to several peer-reviewed literature including high-quality scientific journals, books, and conference proceedings. The study selection consists of five steps (see Figure 1). First, the initial number of publications available in Scopus is extracted: 658 documents were found between 2002 and December of 2023. At the end of the exclusion process, a final set of 201 papers were thoroughly read and classified in this review.

The subsequent section offers a comprehensive analysis of the reviewed literature. Publications were categorized

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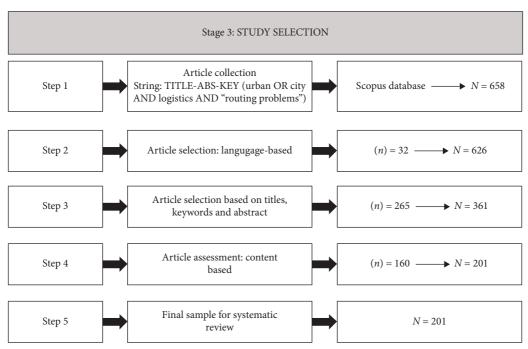


FIGURE 1: Methodology for literature review, Stage 3: study selection and evaluation.

based on various criteria including year, document type, authors, and countries featuring case studies. Furthermore, the documents were sorted according to their modeling approach, solution methods, transportation modes, and performance assessment indicators for delivery networks. Building upon these classifications, the subsequent phase involves detailing the findings of this systematic review and outlining potential research avenues.

3. Descriptive Analysis

Over the last 6 years, research interest in urban logistics operations has grown significantly. The timeframe for this review is 2002–2023, but it is important to note that the search on Scopus using the string defined in the previous section, without any time limit, shows that the first work was published in 2002. Since 2017, the number of documents has increased, reaching its highest point in 2022. The increase in demand for e-commerce and the crisis caused by the pandemic in 2020 could have influenced this growth. About 65% of the papers analyzed in the present study were published between 2020 and 2023 (see Figure 2).

According to the document type, 73% of short-listed documents are journal articles, 24% are conference papers, and 3% are book chapters. The set of journals that published the most about this topic are given as follows (Table 1) The concentration of publications in these specific journals further suggests that urban logistics is primarily being approached from the operational research and transportation perspectives, with a growing shift toward incorporating sustainability aspects. This trend points to the increasing importance of considering both the efficiency and environmental impact of urban logistics systems as urbanization and congestion continue to pose challenges [15].

The authors that published the highest number of papers on this topic are Jairo R. Montoya-Torres (10 papers), followed by Y. Wang (9 papers), H. Wang (8 papers), and finally, X. Wang, Y. Huang, D. Rezgui, H. Bouziri, and W. Aggoune-Mtalaa, who are authors of 6 publications each one within the defined timeframe.

In addition, to identify the most influential works in the field, the top 10 most cited papers were analyzed (see Table 2). These studies, with citation counts ranging from 180 to 110, show a notable increase in publications after 2018, highlighting the growing interest in sustainable and technology-driven logistics solutions. Overall, the findings reveal a shift toward automation, sustainability, and multiechelon distribution strategies, reflecting both academic and industry priorities in technological advancements and environmentally conscious logistics solutions.

Several studies have considered case studies to simulate real-life logistics networks and evaluate the effects of applying the proposed methodologies, the scenarios described and/or employed transportation modes. Among the 201 papers reviewed, there are 101 documents that have used case studies in different countries (50%). Figure 3 shows a world map colored according to the number of case studies per country and their relative frequency. There are 27 different countries in which case studies have been considered: China (28%), the United States (9%), Germany (7%), France (7%), and Italy (6%).

4. Modeling and Solution Approaches

In this section, a description of the modeling approaches and solution methods to deal with routing problems using multiple modes of transportation is presented to answer the two first research questions (Table 3). The former attends to

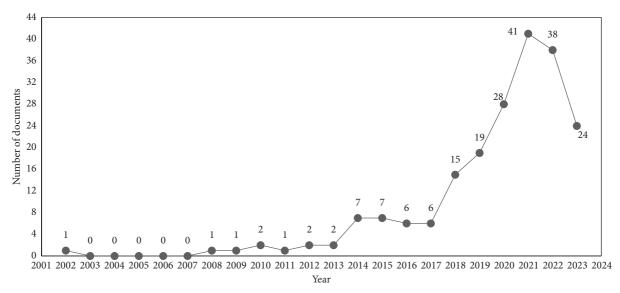


FIGURE 2: Number of papers across the years (2002-2023).

TABLE 1: Number of publications per journal.

Journal	Number of papers
European Journal of Operational Research	14
Transportation Research Part E: Logistics and Transportation Review	11
Sustainability	8
Computers and Operations Research	5
Computers and Industrial Engineering	5
Expert Systems with Applications	5

Table 2: Top 10 most cited papers.

Rank	Reference	Citations
1	[16]	180
2	[17]	179
3	[18]	157
4	[19]	142
5	[20]	142
6	[21]	141
7	[22]	136
8	[23]	127
9	[24]	121
10	[25]	110

the characteristics of the problem regarding the type of routing problem under consideration. Furthermore, the variants of the problem will be addressed. The latter aims to identify the most common solution approaches and trends to generate efficient solutions. The type of problems and the solutions approaches are detailed in the Appendix.

As Cuda et al. [26] explain, there are two types of planning decisions in routing problems: tactical and strategic. Tactical decisions refer to the routing through the distribution network, and for the case of two or multiechelon problems, these decisions include the allocation of customers to the intermediate facilities. Strategic decisions are

related to the network's infrastructure such as the location and number of facilities. The traveling salesman problem (TSP), vehicle routing problem (VRP), and multiechelon VRP involve tactical decisions, while the location routing problem (LRP) and its multiechelon variants involve the strategic decisions of locating the facilities followed by the routing part. In the reviewed literature, 79% of the papers used the VRP as a basis for modeling the research problems; 14% considered the LRP; 3% modeled their problems as the TSP; and the remaining 4% represent studies that modeled their problems as production routing problem (PRP), drone routing problem (DRP) and mixed truck and robot routing

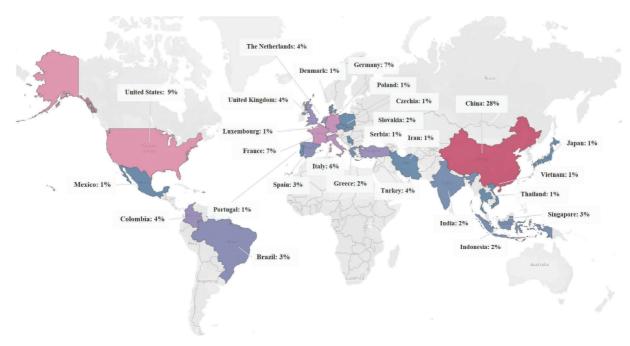


FIGURE 3: Map of the countries where case studies have been evaluated.

TABLE 3: Main results.

Aspect	Findings
Routing problem types	79% VRP, 14% LRP, 3% TSP, and 4% other (PRP, DRP, and MTR-RP)
Planning decisions	Tactical: VRP, TSP, and multiechelon VRP; strategic: LRP and multiechelon LRP
Problem modeling	87% deterministic approximations with rich routing features (time windows, delivery options, synchronization constraints, and green routing)
Problem complexity reduction	Common approaches include simplifications to reduce complexity using deterministic scenarios
Uncertainty consideration	13% of studies address stochastic issues (traffic congestion, energy consumption, and demand fluctuations)
Solution methods usage	84% heuristics/metaheuristics, 25% exact methods (small-medium problems), 11% simulation, and 3% dynamic programming

problem (MTR-RP). In addition, 87% of the studies have chosen to make approximations in their problems to reduce the complexity of the scenarios, addressing them in a deterministic way, by considering rich routing problems that include multiple characteristics such as time windows (one of the most studied) [25], delivery options [27], or synchronization constraints [28]. There are also green routing problems, Wang et al. [29] and Yildiz and Altiparmak [30], that incorporate the minimization of emissions using, in some cases, new transportation modes such as drones, delivery robots, EVs, or heterogeneous fleets that combine them and lead to modifications and adjustments to the problem for their integration.

Real-life urban parcel delivery problems deal with uncertainty in different aspects such as vehicle speed, traffic congestion, fuel or energy consumption, demand, travel times, CO₂e emissions, and delivery time: 13% of the documents addressed stochastic issues. This represents a research opportunity since the inclusion of real-life aspects in these problems is becoming more imperative and is of interest to the community.

Solution methods are also an important topic to consider. They allow the development of decision support systems that could help logistics service providers, dispatchers, and schedulers in making good decisions when solving intracity routing problems. For instance, Ioannou et al. [31] proved that a reduction of over 8% in terms of lost sales can be achieved with the implementation of such tools. Moreover, they have obtained interesting improvements in the number of vehicles and routes. In 84% of the studies, approximation algorithms (heuristics and metaheuristics) are the most applied solution approaches, followed by exact methods (25%) which are usually implemented to solve small-medium sized instances due to the complexity of the problem. Also, simulation approaches are used to solve routing problems with stochastic elements in 11% of the cases. Finally, dynamic programming with 3% of the total articles is considered. Several solution methods have been studied, including hybrid decomposition methods [32], combinations of exact methods and heuristics (mataheuristics) [19], or combination of Monte Carlo simulation and optimization to solve problems with stochastic features

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(simheuristics) [9]. To address large-scale instances, methodologies combining data science and machine learning techniques have been introduced to enable data clustering and optimization using heuristics and metaheuristics to reduce the complexity of the problems [33–35].

5. Multimodal Transportation

This section aims to answer the third research question. Over the years, the use of conventional internal combustion vehicles (ICVs) in last-mile delivery operations has negatively impacted the environment in several ways. The CO₂e generated by these vehicles not only affects the environment but also causes respiratory health problems for city residents [36]. Delivery companies and researchers are paying more attention to reducing emissions to achieve sustainable logistics [37]. Different transportation modes have been evaluated for urban distribution. This section presents an overview of different transportation modes, some of their advantages and disadvantages, and results obtained in the literature.

5.1. EVs. EVs and their charging infrastructure are becoming very popular in major cities around the world. This transportation mode is an environmentally friendly initiative. In urban parcel delivery, the use of EVs is increasing [38] to decrease the negative effects of freight transport on the environment (air pollution, CO₂e emissions, and noise), with lower operational costs compared to ICVs [39–41]. Besides, van Duin et al. [42] concluded that EVs can perform urban delivery in an efficient way, with savings of 19% in terms of distance traveled, as well as reducing CO₂e emissions by 90%.

However, this type of vehicle has some disadvantages such as limited operational range, long charging times, and limited battery capacity [37, 39, 43]. Typically, a fullcharged EV can travel between 75 and 125 miles, but the mileage can be shorter depending on external factors [44]. In fact, the most current EV models exceed 200 miles per charge, and all new models are rated for over 100 miles, with manufacturers announcing plans for even longerrange options in the near future [45]. However, realworld driving conditions often lead to significant range variability. For example, cold weather can reduce range by 20%-30% due to lower battery efficiency and increased energy use for cabin heating. Similarly, high temperatures may cause battery overheating, leading to a reduction in range of up to 20% when air conditioning is heavily used. Road quality and terrain also play a role: uphill driving and poor road surfaces increase energy demand, while downhill segments can partially offset consumption through regenerative braking. Other factors such as aggressive driving, underinflated tires, and heavier payloads further diminish range performance. On the contrary, smooth driving behavior and proper tire maintenance help improve efficiency [46]. Therefore, while battery capacity remains a primary determinant of EV range, operational and environmental variables must be carefully considered

when evaluating their applicability in urban logistics systems when modeling a routing problem [9, 47].

Moreover, the fixed costs associated with EVs are significantly higher than ICVs [41], although their implementation for parcel distribution is more profitable economically and environmentally in the long-term period [48–50]. As Ding et al. [44] explain in their study, different charging techniques are currently available to recharge EVs, for instance, inductive charging, battery swapping, and conductive charging [51]. However, due to the high investment costs of the installation of charging facilities, there is a lack of charging stations for such vehicles in some cities, which causes the inclusion of this type of vehicle to require more time and investment.

5.2. Electric Modular Vehicles (EMVs). EMVs are a type of EVs that have been used for urban parcel delivery [38, 40]. EMVs have one cabin where the driver is located and the cabin can carry several modules, each one has its own battery and so they are autonomous in terms of charging and battery consumption [52]. In addition, having independent modules allows the rest of the EMV to continue the route without carrying all the modules, which means that modules can be removed if their battery level is insufficient or when there are length restrictions for vehicles in urban areas.

5.3. Autonomous Vehicles (AVs). AVs have begun to be employed and studied to support urban last-mile distribution. The literature has often focused on passenger mobility over urban delivery [53]. According to the authors in [54], autonomous ground vehicles were especially tested within pilot projects to investigate the feasibility as well as customer acceptance. The study proposed by the authors in [55] exposed that the application of this type of vehicle in freight transport presents better opportunities in terms of operational complexity compared to passenger transport because it represents greater cost-efficiency in a very competitive field, and there can be repetitive and predictable routes that would reduce engineering complexity. Experiments conducted by the authors in [56] conclude that the use of AVs can increase the efficiency of last-mile freight delivery in terms of route time by up to 30%.

5.4. Delivery Robots. Autonomous delivery robots are designed primarily to travel short distances; they can avoid obstacles located on the sidewalk autonomously. However, the length of their delivery route can be impacted by the obstacles that the robot can find on the way to the destination. While these robots can assist with last-mile delivery, they are not suitable for handling entire delivery operations, as they can only carry small- to medium-sized packages.

A case study in Xi'an city in China, demonstrated the use of delivery robots to serve areas with van access restrictions such as pedestrianized sidewalks or city campuses [57]. Similarly, in Cardiff, United Kingdom, robots are deployed to travel along sidewalks and deliver parcels to residents in urban areas [21]. These robots present a valuable solution for

reducing emissions, personnel costs, urban road traffic, land use, and noise. Moreover, they can visit areas that can be restricted to vans [54, 58, 59]. The COVID-19 pandemic further highlighted their advantages, as self-driving robots can ensure social distancing, protecting both the delivery personnel and customers [21]. In addition, these robots are electronically secured, meaning that customers can only access their parcel through an individual code, ensuring security [54].

Despite these benefits, several limitations hinder the broader use of autonomous delivery roots. Their limited load capacity, speed, and operational range constrain their ability to handle larger or more complex deliveries [60]. Moreover, practical challenges arise as some customers, particularly the elderly or disabled, may be reluctant to interact with the robots, and some parcels may be too large, risky, or hazardous to be delivered by them. As a result, these robots are often used in combination with standard van deliveries to optimize the process. By combining both transportation modes, delivery efficiency improves, reducing overall travel time and costs [19]. Some experiments show that this integration can lead to cost reductions of up to 43% compared to traditional delivery methods [61].

5.5. Unmanned Aerial Vehicles (UAVs). UAVs, also referred to as drones, have become an interesting option to assist the delivery by big companies such as DHL and Amazon [62] and have also been widely studied recently as a component in freight delivery routing problems [63]. According to the authors in [64], UAVs' routing "is a potential game changer in solving the urban air mobility challenge by allowing to reshape transportation and logistics in the future" (p.1). Compared to traditional vehicle distribution, drones are more flexible and low-cost, can avoid road traffic restrictions due to congestion or accidents, are lightweight, and carbon emissions are lower [65, 66].

However, UAVs have some challenges in real-life applications: bad weather, flying restrictions, limited delivery range (10–30 km) due to their battery capacity, and payload limitations [66–70]. In some cities, there are some no-fly areas that are inaccessible by drones such as the airports, power plants, and government buildings [71]. Also, cities with dense high-rise buildings, e.g., New York in the United States of America, are very challenging for drones due to the difficulties of maneuvering [72].

According to the authors in [73], between 10% and 25% of Amazon deliveries cannot be handled by aerial drones, due to size restrictions. To address this limitation, different scenarios have been proposed in the literature introducing alternatives to take advantage of this transportation mode in urban logistics. For example, Jeong and Lee [70] explored the possibility of drones carrying multiple parcels per trip providing both pickup and delivery services to increase their utilization rate. In addition, researchers have studied the integration of drones with other transportation modes, such as trucks and delivery vans, to enhance operational effectiveness [74, 75].

Huang et al. [76] demonstrated that collaborative freight delivery using both drones and trucks can successfully reduce costs, CO₂e emissions, and delivery times. Case studies in Seattle and Buffalo, in the United States [70]; Izmir, Turkey [66]; and in Changsha, China [74] examined the use of drones in areas where customer locations are difficult to reach due to high congestion and carbon-dense environments, helping to mitigate the environmental impact of road transportation. Some studies have also explored hybrid approaches, where drones and trucks operate together to optimize logistics operations. For instance, in Changsha, drones deliver parcels directly to customers, while trucks not only handle certain deliveries but also supply drones with parcels and batteries, ensuring continuous operations [74].

5.6. Cargo Bikes. In the context of more sustainable deliveries, cargo bikes are gaining popularity in several cities. Mühlbauer and Fontaine [77] presented the use of cargo bikes as a promising alternative to conventional vans for parcel delivery in urban logistics. This transportation mode requires less parking space, and congestion can be reduced if cargo bikes use bike lanes or other road infrastructure available. Cargo bikes can have between 2 and 4 wheels, and the payload can be positioned in the front or in the back of the vehicle. Also, cargo bikes are emission-free in terms of direct CO_2 e emissions, NOx, and particulate matter and emit less noise than conventional vehicles [78]. The use of cargo bikes for parcel distribution can save between 19% and 38% of CO2e emissions, so delivery operations become more sustainable than the conventional urban parcel distribution systems [77]. Electric cargo bikes (e-cargo bikes) have also been considered; they contain electric batteries that allow a distance range of 50 km [79]. Thanks to the battery, they can be charged very fast and can be used under tough conditions for normal cargo bikes, such as steep slopes and strong winds [80]. Cargo bikes and e-cargo bikes can replace conventional delivery vans because they are able to access and supply urban areas restricted to vans such as sidewalks, narrow streets, and historic centers [81].

However, when exclusively delivering using cargo bikes, the drawbacks are related to the extensive use of public land space. Moreover, travel speed depends on the load, the distance that can be covered, the street topography, and the reduced load capacity [82]. So, this transportation mode is commonly used in the second level of two-echelon distribution systems. Cargo bikes can save up to 10% of costs [77] but should be combined with other transportation modes (e.g., delivery vans either electric or fuel-based) to transport the freight needed to be delivered to remote areas or large distances to truly benefit their advantages.

5.7. Public Transport. The use of public transport networks for both passengers and freight is also being explored in the literature, including metro lines [83, 84] and freight buses [85–88]. Case studies from cities such as Singapore, which boasts an extensive and highly efficient public transportation

system [89], and Nanjing, where the underground metro network spans 378 km with 10 lines and 174 stations, highlight the potential of urban transit systems. Nanjing's metro system is considered one of the most advanced urban rail transport systems in China [90]. These studies demonstrate how integrating public transportation systems with freight services could replace the need for city freighters operated by private third-party logistics companies in innercity areas. This integration could lead to significant reductions in logistics costs, air pollution, and traffic congestion [91].

On one hand, freight buses can pick up or deliver parcels at each location they pass, and their use can improve the accuracy of logistics services because they have fixed time schedules and can improve the utilization rate of the roads reserved for buses [86]. He and Yang [88] considered buses as a supplementary delivery alternative in parallel with trucks. It means that some parcels are delivered by buses instead of trucks to reduce the number of trucks or the number of trips by truck, leading to a reduction in delivery costs and CO₂e emissions and an increase in bus utilization. On the other hand, the use of urban rail transportation systems (e.g., metro lines) has very great advantages compared to conventional deliveries in terms of costs and service quality. However, it is important to note that the use of metro lines is supplementary and requires the use of other transportation modes as a complement for the distribution network. For instance, the authors in [84] introduced a three-stage delivery network in which trucks are in charge of transporting parcels between the supplier and the metro entry station (first stage), the second stage is the route between the metro entry station and the metro exit station (metro delivery), and the third stage corresponds to routing delivery vans from the metro exit to the delivery points.

If the public transport system is well utilized, it could be possible to also have some passengers to make crowdsourced delivery (also known as crowdshipping), which is the use of the crowd (pedestrians) for parcel delivery. Zhang et al. [92] analyzed a case study in Singapore with public transit passengers as crowdshippers. Results show that crowdshipping has a great potential to be a sustainable means for urban parcel delivery even if it is only implemented in offpeak hours: emissions and distance can be reduced by up to 17% and savings in delivery costs can reach 29% per parcel.

5.8. Mixed Transportation Modes. According to the findings from the literature, the combination of multiple modes of transportation is especially beneficial in medium and large cities with high population density and rapid, continuous growth. These cities often face challenges such as traffic congestion and access limitations across various areas. Such conditions make it difficult to maintain efficient transportation systems, which in turn can affect urban mobility and logistics.

Among the case studies analyzed are major cities such as Austin, United States, with an annual growth rate of approximately 3% [93], where the combination of cargo bikes, EVs, and ICVs was studied to improve urban logistics and

reduce congestion. Chongqing, China's youngest municipality, recognized for its unique geography featuring rivers and mountains that divide the city into numerous distinct areas [94], has also been a case study in several papers. These studies have evaluated the combination of various vehicles, including EVs, drones, and trucks, to optimize distribution networks and overcome the city's complex topography. Chongqing is one of the most densely populated cities in China, with a population exceeding 18 million [34].

In cities such as these, the integration of mixed transportation networks, including vehicles that can navigate different urban environments, is a crucial strategy. These transportation systems provide more efficient access to hard-to-reach areas, ensuring smooth logistics operations. In addition, they contribute to reducing the negative impacts of congestion, offering sustainable solutions for urban mobility. This approach supports the growth of smart city infrastructure and enhances overall city resilience in the face of rapid urbanization.

There are other interesting studies that provide evidence that the combination of different transportation modes is necessary to strengthen last-mile delivery, reducing costs, time, and emissions. For example, combining electric ships with cargo bikes can cut CO₂-equivalent emissions by roughly 78% (Alewijnse and Hübl, 2021). Other promising multimodal strategies include the following: - cargo bikes supported by crowd-shipping—an environmentally friendly option that may, however, reduce delivery efficiency (Perboli et al., 2022); - autonomous vehicles working in concert with cargo bikes and pedestrian couriers (J. Li et al., 2021); public-transport- based crowd-shipping operated in parallel with delivery vans (Zhang et al., 2023); - mixed fleets of delivery robots and vans (Chen et al., 2021; Ostermeier et al., 2023); - cargo bikes paired with vans (Simoni et al., 2018); and - truck-and-drone systems (Huang et al., 2022). Liu et al. (2023) add that close coordination between trucks and drones is a key to scaling up drone use in the last mile, offsetting drones' inherent limits in payload capacity and range.

Also, several logistics service providers such as UPS and DHL use in their fleets a mix of transportation modes for freight delivery in urban areas to add more flexibility and have access to inner-city areas with restrictions on the type of vehicles and to allow a reduction of CO₂e emissions [100, 101]. From the documents analyzed in this study, Figure 4 presents a categorization of transportation modes based on size, energy source, and autonomy level. The colored circles indicate the frequency of use of each transportation mode in the literature, showing that trucks (ICVs), delivery vans, EVs, and UAVs are among the most studied options. However, there are research opportunities regarding the use of water vehicles, urban rail transportation, public transport, AVs, and motorcycles, which remain underexplored.

The comparative analysis between the two periods (2002–2012 versus 2013–2023) reveals a clear shift in transportation trends. During 2002–2012, fuel-based and driver-operated vehicles, such as trucks and delivery vans, were predominant in logistics studies. In contrast, the last

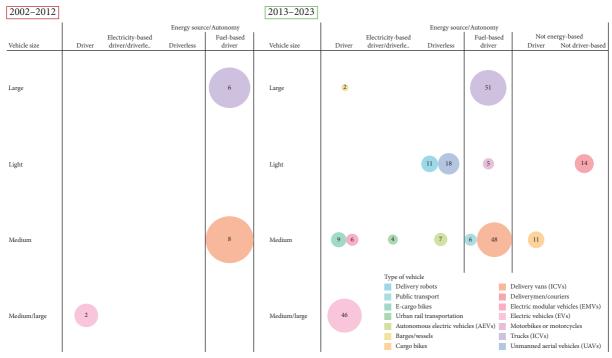


FIGURE 4: Evolution and classification of transportation modes by energy source, autonomy, and vehicle size: a comparative analysis (2002–2012 vs. 2013–2023).

decade (2013–2023) has seen the rise of more sustainable and autonomous technologies, including EVs, EMVs, ecargo bikes, delivery robots, and UAVs. This evolution reflects the increasing emphasis on sustainability, automation, and efficiency in urban distribution networks. The difference in circle proportions reflects the rise in publications over time. While 2002–2012 research focused on fuel-based trucks, research between 2013 and 2023 shows growing interest in EVs, autonomous transportation modes, cargo bikes, and drones, highlighting the shift toward greener and more efficient last-mile solutions.

In addition, the selection of transportation modes in specific distribution networks depends on various factors, including the city's infrastructure, geographic characteristics (e.g., the feasibility of using ships or rail networks), public policies related to urban distribution, and access or parking restrictions in certain areas. Ensuring the optimal implementation of transportation modalities requires considering these elements to improve logistics efficiency, reduce congestion, and minimize environmental impact.

6. Performance Indicators

This section presents the findings about the performance indicators considered in the literature to measure the performance and the sustainability of the proposed scenarios. This section hence approaches to answering the last research question. Indicators to assess environmental, economic, logistics, and social issues as well as algorithmic performance are analyzed. An overview of the findings is presented in Table 4. For a detailed classification of the

KPIs and their corresponding references, please refer to the Appendix and a detailed description is presented in Section 6.1.

Indicators are grouped not only by domain (economic, environmental, social, logistics, and algorithmic) but also by their underlying logic and contribution to the sustainability and operational efficiency of urban distribution systems. The selection and categorization of indicators are based on a functional coherence: each group aims to measure distinct but complementary aspects of the system. For example, while economic indicators reflect financial performance, environmental indicators assess ecological impact, and social indicators focus on human well-being and societal externalities. These dimensions, although studied separately, are inherently interconnected and support the multidimensional evaluation of the proposed scenarios.

Furthermore, measurement in this context implies more than listing indicators; it requires an understanding of how these indicators interact, complement, and occasionally contradict each other. For instance, minimizing costs may conflict with maximizing service level or reducing emissions. Therefore, the indicators selected for the analysis should be understood as part of a broader evaluative framework where trade-offs are inevitable and must be transparently addressed.

6.1. Economic Indicators. As Pugliese et al. [62] mentioned in their study that "parcel delivery is the most expensive phase of distribution logistics" (p. 488). That is why, it is very important to minimize costs without compromising the efficiency and productivity of the system. This group of

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TABLE 4: Classification of performance indicators by algorithm performance, environmental, economic, logistics, and social.

Category	Subcategory	Indicator
Algorithm performance		CPU time, computing time, elapsed time, runtime, running time, mean ideal distance, diversification metric, gap (%), standard deviation, and computing efficiency
Environmental	Emissions Use of resources	CO ₂ e emissions, GHG, CO, NH ₃ , N ₂ O, NOx, PM2.5, noise emissions, noise levels, and fine particle emissions Energy/fuel/electric power consumption, electric consumption, number of times EV is charged, total number of battery swaps requested, cyclist energy, battery energy, and recharged energy
Economic		Fuel consumption costs, emissions costs, carbon emissions cost, total fleet operation costs, fixed usage cost of the vehicle, maintenance costs, total distribution costs, operating costs, fixed costs, investment costs, charging costs, battery swapping costs, profits, cost improvement, cost savings, variable cost due to delays, penalty cost, cost of time window violation, total costs, drivers salary costs, customer service costs, electric delivery cost, penalty costs, facility operation costs, and load-distance costs
	Productivity	Route length, total distance traveled, real distance, travel distance, distance, net mileage, travel time, distribution time, delivery time, number of parcels/packages, parcels per route, total weight of parcels, covered customer rate, total utilization rate of the recharging station, crew size, and demand fulfillment rate. Average number of chargers, number/amount of stops, number of customers, delivery points per route, number of stations, number of shared charging stations.
Logistics	Infrastructure Time	number of used covering locations, number of served nodes, number of number of intermediate depots/satellites, and number of split deliveries Waiting/delay times, charging times, battery swapping times, EV queuing times for charging, route duration, tour time, and total working time
	Transportation modes	utilization, vehicle loading rate, average load, number of subfleets, and number of routes/paths
Social		Disturbance, risk of accidents, average delay per customer, service delay, delays, congestion index, traffic congestion, service level, land use, occupation of the area, and customer satisfaction

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indicators comprises all fixed and variable costs related to the operations of the distribution network under study. Also, it includes investment, maintenance, and operational costs of vehicle fleets, as well as vehicle fuel and energy costs, penalty costs due to delays and lost sales, savings, profits, and workers' salaries. It is important to highlight that some works consider energy costs and workers' salaries as environmental or social metrics, respectively, but we decided to keep these as economic indicators since they translate to a monetary impact for the enterprises.

It is important to note that when the indicator is the total cost, it is pertinent to be aware that it is necessary to examine which costs are being included in this indicator, since it will depend on the configuration of the distribution network, the type of decisions involved, as well as additional characteristics particular to each case study. This indicator is very useful to determine the total cost incurred by operating under such a scenario; nevertheless, a comparison between the total cost indicator of one study versus the total cost of another is not reliable if the same items were not considered in both studies. For instance, in the context of EVs, Fan [102] defined the total distribution cost as the costs of EVs' dispatch, vehicle travel, customer service, and charging operations; while for Wang et al. [113], total costs involve the opening costs and handling costs for parcel lockers and the routing costs of the EVs.

- 6.2. Environmental Indicators. The purpose of these indicators is to evaluate the impact on the environment of the emissions generated by the transportation modes. This impact depends significantly on the type of energy source used to power vehicles. For this reason, we can classify the environmental indicators into two subgroups. The first refers to the emission types, while the second is related to the use of resources (energy) required by the transportation modes to perform delivery activities. These are explained next.
- 6.2.1. Emissions. According to the authors in [29], green logistics is becoming extremely important due to its impact on the environment and society. Its aim is the minimization of carbon emissions because conventional transportation systems are unsustainable and can also affect the population's respiratory health and worsen the problem of climate change [36]. For instance, the $\rm CO_{2}e$ emissions that are generated by the fleet of vehicles comprise $\rm CO_{2}$, methane (CH₄), and nitrous oxide (N₂O) emissions [92]. Such indicators are very important to measure the sustainability of the urban distribution networks proposed in the literature.
- 6.2.2. Use of Resources. This group consists of indicators to control the use of resources such as electric power, diesel, fuel, or gasoline. In addition, the study conducted by Fontaine [82] considers indicators such as cyclist's energy and the energy of the batteries that power some transportation modes such as EVs, delivery robots, UAVs, and ecargo bikes. Moreover, the authors in [89] estimated the

energy consumption based on the multiplication of the distance traveled by the vehicle and the kilowatt-hour (kWh) per mile or kilometer.

6.3. Social Indicators. Delivery activities do have a high influence on society. Social impacts of urban distribution systems can be measured in terms of the risk of accidents, the occupation of public space (land use), the congestion index or traffic congestion, or the disturbance due to noise and congestion [81]. Since customer satisfaction in lastmile distribution is mainly evaluated based on delivery time windows, the service level can be evaluated. Hence, late delivery causes customer dissatisfaction, so indicators such as average delay per customer and customer satisfaction are very important in these cases. Cao et al. [120] explained that in the VRP time windows, "the time of obtaining service for a certain customer is in the determined range, which means that the service level is good (1), otherwise it is bad (0). However, in real-life problems, time windows can be violated" (p. 2511) for various practical considerations.

Economic and productivity indicators are the most studied in the literature, while there is a lack of research that includes social indicators to assess the distribution networks. This represents a research perspective since this is a very important pillar of sustainability. The adoption and evaluation of indicators that are related to city inhabitants, drivers, delivery persons, or similar directly or indirectly related to urban distribution are key elements of a sustainable urban logistics system.

- 6.4. Logistics Indicators. The traditional dimensions of sustainability consider only economic, social, and environmental indicators. However, in urban transport systems, there are indicators related to logistics elements that may not perfectly suit the definition of the three previous categories. So, following the rationale proposed in [212], we also considered this fourth category, named "logistics indicators," to characterize some performance metrics that are related to the performance of the delivery operations (productivity and time), the vehicles' fleet size, and the infrastructure used to execute these activities. This is explained next.
- 6.4.1. Productivity. Measures of productivity of urban distribution networks are crucial for making the right strategic or planning decisions. This kind of indicator allows an overall assessment of the distribution network performance and, if there are scenarios, it is also a way to compare them to check their feasibility and possible implementation. For instance, the route length is the number of kilometers that a vehicle must travel to complete a route or tour. To analyze the global results of a distribution network, the total distance traveled is very useful. If the study is time-dependent, the total travel time, also called delivery time or distribution time, is the total time that all the fleet requires to deliver all parcels in a workday. In addition, the number of parcels delivered is

a good indicator to measure the productivity of the distribution network. Finally, the covered customer rate allows decision-makers to know how many customers a route is serving and can be calculated as the number of served customers divided by the total number of customers [120]. Moreover, it is important to know how many delivery persons (crew size) are needed to perform the delivery activities.

6.4.2. Infrastructure. Since urban distribution systems require a well-designed infrastructure to operate efficiently and to serve as many customers as possible, it is important to define performance indicators that also allow the quantification and measurement of different aspects such as the number of recharging stations [213] or the number of depots or distribution centers. This group also comprises the number of customers or nodes served and the number of times the vehicles must stop delivering parcels.

6.4.3. Time. These are all indicators that are related to time-dependent parameters. Within this subgroup, there are indicators such as route duration, which is the time that a transportation mode takes to complete a route or tour. Besides, waiting times are also considered [191]. In addition, in the context of an electric VRP, Xu et al. [43] defined that the total working time includes travel time, charging time, waiting time, and service time.

6.4.4. Transportation Modes. This includes all indicators related to the use and the features of the vehicle fleet, such as fleet size, traffic flows (i.e., amount of vehicles/ships per day) [95, 214], vehicle loading rate, the number of routes per day, and the number of subfleets (e.g., number of truck versus number of drones) [76].

6.5. Algorithm Performance. Measuring the performance of algorithms that allow researchers and decision-makers to find solutions to routing problems is crucial since reaching optimality can be very computationally expensive due to the nondeterministic polynomial (NP)-hardness of these routing problems. Therefore, indicators such as central processing unit (CPU) time are considered in several papers. Finding a good solution, preferably the optimum, in a short computational time is highly desirable. Also, the gap between lower bounds and upper bounds is usually applied to compare solution approaches. Sarbijan and Behnamian [111] introduced indicators such as mean ideal distance and the diversification metric. In multiobjective optimization problems, the former computes the average distance of the Pareto solutions from the ideal point. The lower this metric, the better the algorithm's performance. The latter is the distance between the initial and final solutions of the Pareto solutions. The larger its value, the more efficient the algorithm.

6.6. Interrelation Among Indicators. Performance indicators, although organized by distinct categories, rarely operate in isolation. On the contrary, they often interact and

may even conflict with one another, reflecting the inherent complexity of evaluating urban distribution systems. Understanding these interrelations is essential not only for analysis but also for effective decision-making and policy design.

First, economic and environmental indicators frequently present trade-offs. For instance, minimizing operational costs may involve using conventional vehicles instead of electric ones, which in turn increases carbon emissions. Similarly, reducing delivery times (a logistics indicator) may require a larger fleet size or more frequent trips, thus raising both economic costs and environmental impacts. These examples highlight how optimizing one dimension can produce unintended consequences in another, emphasizing the need for integrated assessment.

Second, social indicators such as service level or noise disturbance are deeply affected by logistics and economic decisions. A higher service level often demands narrower delivery windows and increased vehicle frequency, which can escalate congestion and emissions in urban areas. In addition, the occupation of public space (e.g., for loading/unloading or placing lockers) might enhance efficiency but simultaneously reduce urban livability, posing a societal dilemma between efficiency and quality of life.

Moreover, logistics indicators serve as mediators between operational objectives and sustainability outcomes. Route length, fleet size, and travel time are not only efficiency metrics but also directly influence fuel consumption, emissions, and service reliability. As such, they often act as bridging variables across economic, environmental, and social domains.

In this context, it becomes essential to interpret indicators within a multiobjective framework, where tradeoffs are made explicit and can be evaluated according to stakeholder priorities. Multicriteria decision analysis (MCDA) and Pareto optimization approaches are particularly useful in addressing this complexity, as they allow decision-makers to evaluate multiple competing objectives simultaneously rather than seeking a single optimal solution.

7. Conclusions and Research Perspectives

This paper presented a comprehensive systematic literature review on urban logistics and routing problems, focusing on three main aspects: problem modeling and solution approaches, multimodal transportation, and performance indicators to assess the sustainability and efficiency of the delivery networks. The review highlights significant trends and findings from diverse case studies and identifies key methodological and technological trends shaping the field.

Recent methodological trends show a shift toward more advances and integrated approaches. While the VRP, particularly with time windows, remains the dominant modeling approach, recent studies increasingly incorporate green routing, delivery synchronization, and multimodal delivery components. Stochastic modeling remains underexplored, representing an opportunity for

future research to better address real-world uncertainties such as fluctuating traffic conditions and dynamic delivery demands. Hybrid optimization techniques, including matheuristics, simheuristics, and machine learning-assisted heuristics, are becoming prominent as data availability increases in smart city settings, allowing for more efficient and adaptive decision-making processes.

The review also revealed important patterns in case study applications and data usage. Approximately 50% of the reviewed studies utilized case studies to test urban logistics models under real-world conditions, primarily located in China, the United States, and Western Europe, with developing regions underrepresented. Data sources vary significantly, ranging from empirical fleet operations to simulation-based datasets, with key input variables including vehicle types, delivery demand, fuel/ energy consumption, and congestion levels. The findings consistently indicate that multimodal transportation networks, integrating EVs, drones, cargo bikes, and public transport, offer significant reductions in CO2e emissions, costs, and congestion compared to conventional delivery methods. However, barriers to large-scale implementation persist, including infrastructure limitations, regulatory restrictions, and cost concerns related to charging stations, battery life, and operational constraints.

Different technologies in terms of transportation modes have been applied to support urban logistics networks, some are more sustainable than others, or guarantee access to restricted areas in cities. An analysis in this regard was also made, highlighting some of the advantages and disadvantages of EVs, EMVs, AVs, delivery robots, UAVs, cargo bikes, and shared public transport systems. Moreover, the combination of different transportation modes is necessary to strengthen last-mile delivery, reducing costs, time, and emissions. In addition, to ensure the implementation of the most appropriate transportation modes, it is important to analyze multiple factors such as the infrastructure of the city under study, geographic characteristics (e.g. topography and use of ships or rail networks), the public policies related to urban distribution, the access to and/or limitations in parking, and the demand of the distribution network. The integration of multimodal transportation has gained momentum, driven by environmental concerns and urban accessibility challenges. Studies show that the combination of EVs, delivery robots, drones, and shared public transport systems can enhance delivery efficiency while reducing

In terms of performance evaluation, the study presented a detailed classification of indicators used to assess the threedimensional sustainability of urban delivery systems. A classification of five important aspects was made as follows: (1) algorithm performance, (2) environmental indicators (emissions and use of resources such as energy or fuel), (3) economic indicators, (4) logistics indicators (productivity, infrastructure, time, and transportation modalities), and (5) social indicators. In addition, the study of performance indicators has evolved to include not only economic and environmental metrics but also social sustainability indicators, such as land use, congestion levels, and customer satisfaction. The growing inclusion of social metrics represents a positive trend toward holistic assessment, though more research is needed in this area.

In response to the review findings, this study offers the following detailed conclusions regarding urban logistics research:

- The most commonly studied problem is the time window VRP, often expanded with multimodal, synchronization, or sustainability objectives.
- About half of the papers use real-world case studies, but most are limited to developed countries.
- EVs, UAVs, delivery robots, and cargo bikes are frequently evaluated as alternative transport modes, especially in combination.
- The most frequently used performance indicators are emissions, cost, energy consumption, and delivery time.
- Less than 30% of the studies include social indicators, which indicates a research gap.

Several research gaps were identified: (1) the limited use of stochastic and uncertainty-based modeling, (2) the need to diversify the geographical focus of case studies, (3) the opportunity to enhance multimodal delivery through AI and real-time optimization, and (4) the underrepresentation of social impact evaluation in logistics models.

In summary, this review provides a structured overview of the current state of urban logistics research, uncovering clear patterns in methodological preferences, technological adoption, and the evaluation of sustainability practices. The predominance of optimization-based approaches, the growing interest in hybrid heuristics, the increasing attention in multimodal transport integration, and the gradual inclusion of social indicators highlight the ongoing evolution of the field, while also exposing gaps and inconsistencies in certain areas. The thematic classification developed in this paper enables a more coherent understanding of how modeling approaches, transport technologies, and sustainability metrics interact. This framework not only facilitates comparative analysis across studies but also supports practitioners and researchers in identifying practical strategies and unexplored research avenues aligned with the goals of sustainable urban logistics systems.

Appendix

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TABLE A1: Types of problem and the solution approach for each study.

102 TDOEVRP-HERS 80 CVRP 98 MVTR-RP 60 DVRPSPD and MDVRPSPD and MDVRPSPD and MDVRPSPD and MDVRPSPD and MDVRPSPD and MDPHOTDEVRP 104 MDHOTDEVRP 106 CMEVRPTW - SCS 107 Multi-facility LRP 108 2E-VRP 1109 2E-VRP 2E-VRP 60 2E-LDVRP-MV 89 CVRP 94 MD-2E-JDLRP 50 CVRP 69 LRP-PS 1110 DRP-HD 69 LRP-PS 1111 EVRPTW 112 EVRPTW 60 LRP-PS 1112 EVRPTW 61 MTR-RP 112 EVRPTWRS 113 EVCSLRPTWRS 113 EVCSLRPTWRS 114 EVRPTW-DC 114 EVRPT	x x x x x x x x x x x x x x x x x x x	×××× × ××× × ×	MIP and a hybrid adaptive large neighborhood search (HALNS) Genetic algorithm (GA) Tailored heuristic based on a novel neighborhood search: set improvement neighborhood search (SINS) Hybrid Q-learning network-based method (HQM)-reinforced learning MILP and simulated annealing (SA) with path encoding and acceleration strategies GRASP with a restricted candidate list (RCL) and SA and variable neighborhood search (VNS) MILP and two-phase metaheuristic (TPH)-greedy construction algorithm and hybrid VNS-SA MIP and two-stage hybrid ant colony algorithm (TSHACA) MINP and ALNS Hybrid algorithm Gaussian mixture clustering and improved multiobjective GA with Tabu search (TS)
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		× ×××× × ×	MILP and simulated annealing (SA) with path encoding and acceleration strategies GRASP with a restricted candidate list (RCL) and SA and variable neighborhood search (VNS) MILP and two-phase metaheuristic (TPH)-greedy construction algorithm and hybrid VNS-SA MIP and two-stage hybrid ant colony algorithm (TSHACA) MINP and ALNS Hybrid algorithm Gaussian mixture clustering and improved multiobjective GA with Tabu search (TS)
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		×	(INTOXITY) Exact annioach based on nartitioning of the research snace of the solutions of a MII P model
	· >		Memetic algorithm with constructive henristic (MACH), evolutionary-based structure
	>	×	Decomposition approach combining k-means clustering and the nearest neighbor (NN) search heuristic
	>	;	Decomposition approach combining k-means clustering and the NN search heuristic to obtain initial
	>	×	solutions, improvement phase of relocate local search (RLS)
	<	×	Two-phase approach: clustering phase and mathematical model and heuristic with intelligent dispatch
		×	Scheme Cluster-based artificial immune algorithm (C-AIA)
	>	<	
	<	×	
		: ×	Immune algorithm (IA) and improved nondominated sorting GA-II (IA-iNSGA-II)
		×	Improved ant colony optimization algorithm (IACO)
		×	Hyperlocal-drone neighbor search heuristic (H-DNSH)
	×		Branch-and-price algorithm
		×	Multiobjective particle swarm optimization algorithm and VNS (MOPSO-VNS)
		×	A two-phase heuristic approach combining a two-layer genetic algorithm (TLGA) and simulated
		<	annealing (SA)-TLGALS
		×	Variable neighborhood search (VNS)
		×	Iterative local search (ILS)
		×	Hybrid algorithm combining the Gaussian mixture clustering algorithm (GMCA) with the improved
		×	Adantive particle swarm ontimization (PSO)
[115] I.RP		: ×	Variable neighborhood descent (VND)
CI		^ : ×	XNV X
	×		Modified C&W with
[53] VRP	×		
[118] GVRPTW		×	Hybrid heuristic
[119] LRP		^	Hybrid Lagrangian relaxation and alternating direction method of multipliers (LR-ADMM)
[120] GVRP-PCPS		×	Memory-based VNS
		× ×	GA GA

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TABLE A1: Continued.

[25] CAVIARDCDTVK N Improved kandeding desenting algorithm and inspection altacle sevent optimization optimization (S-GAIIPSO) [126] MUNARTVA X Input of postal plant in serion in strengy (MORPOS DIS) algorithm [124] ALVERPOAR X VARABATA [124] ALVERPOAR X VARABATA [124] ALVERPOAR X X [125] ALVERPOAR X X [126] ALVERPOAR X X [127] ALVERPOAR X X [128] ALVERPOAR X X [128] ALVERPOAR X X [129] ALVERPOAR X X [12] ALVE	Reference	Problem	Exact methods	Simulation	Approx algorithm	Approx Dynamic algorithm programming	Solution approach
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MDVRPTW WRP WRP WRP MD-CVRR-OSA DSVRPTW 2E-VRHPD 2E-VRHPD 2E-VRHPD 2E-VRHPD 3E-VRHPD 3E-VRHPD 3E-VRHPD 3E-VRHPD 3E-VRHPD 3E-VRP WO-CRPTW-mD 3E-VRP WO-CRPTW-mD 3E-VRP WRPTTW 3E-VRP WRPTTW 3E-VRP SE-VRP WRPTTW 3E-VRP WRPD CSPTW-TN-DO 3E-SPTRP WRPD CSPTW-TN-DO 3C-SPTW-TN-DO 3C-SPTW-TN-DO 3C-SPTW-TN-DO 3C-SPTW-TN-DO 3C-SPTW-TN-DO 3C-SPTW-TN-DO 3C-SPTW-TN-DO 3C-SPTW-TN-DO 3C-SPTRP WRP WRP WRP WRP WRP WRP WRP WRP WRP W	[67]	CM V KFDCD I W			×		based on the dynamic insertion strategy (IMOPSO-DIS) algorithm
VRP X AD-CVRP-OSA X DS-VRPTW X 2E-VRP X 2E-VRP X YRP X Mo-CRPTW-mD X TSP X VRPTTY X VRPTTW X VRPTTW X VRPTTW X EVRPSPD-NL-LD X CHRPSPD-NL-LD X CHRPSPD-LF X OMDPDTW-VRP X VRPD X URP X LRP X VRP X URP X VRP X URP X VRP	[122]	MDVRPTW			×		Hybrid algorithm of genetically improved set-based particle swarm optimization (S-GAIPSO)
2E-EVRP-TW MD-CYRP-OSA DSVRPTW 2E-VRP 2E-VRP 2E-VRP 2E-VRP 3E-VRP	[36]	VRP			×		Adaptive large neighborhood search (ALNS)
MD-CVRP-OSA DSVRPTW 2E-VRP 2E-VRP VRP Wo-CRPTW-mD TSP VRPITT VRPTTW EVRPTW-RS-SMBS VRPTW VRPTW VRPD VRPD VRPD VRPD VRP VRP VRP	[123]	2E-EVRP-TW			×		SNA
DSVRPTW 2E-VRPP 2E-VRP 2E-VRP No-CRPTW-mD TSP WO-CRPTW-mD TSP WO-CRPTW-mD TSP VRPTTY VRPTTY VRPTTY EVRPSPD-NL- LD SLE-VRP SCANTON VRPD VRPTTY VRPD VRPTY VRPD VRPD VRPD SLE-VRP CIRP-DO VRP VRPD VRP VRP VRP VRP VRP VR	[124]	MD-CVRP-OSA			×		NNS
2E-VRP × 2E-VRP × VRP × Mo-CRPTW-mD × YRPTT × VRPTW × VRPTW × VRPTTW × VRPTTW × VRPTTW × VRPTTW × VRPTTW × VRPD-NG-NG-NG-NG-NG-NG-NG-NG-NG-NG-NG-NG-NG-	[96]	DSVRPTW		×	×		Monte Carlo simulation and LNS
2E-VRP × YRP × Wo-CRPTW-mD × YRPTTW × VRPTTW × VRPTTW × VRPTTW × EVRPTW-RS-SMBS × VRPTT × VRPTTW × CLRP-DO × VRPD × CLRP-DO × VRP × OMDEDTIV-VRP × VRPD × CSPTW-TN-DO × VRP × LRP × VRP × <td>[57]</td> <td>2E-VRHPD</td> <td></td> <td></td> <td>×</td> <td></td> <td>ALNS</td>	[57]	2E-VRHPD			×		ALNS
2E-VRP × VRP × Mo-CRPTW-mD × TSP × VRPLTT × VRPTW × VRPTWV × VRPTWV × VRPLTT × VRPLTT × VRPLTT × VRPLTT × CLRP-DO × VRP × CLRP-DO × VRP × OMDPDTW-LP × VRP × CSPTW-TN-DO × DS-EVRP × LRP × VRP ×	[33]	2E-VRP			×		2D-K-means, nearest neighbor heuristic (NN) with local search operators
WRP × Mo-CRPTW-mD × TSP × WPPTTY × VRPTTW × VRPTTW × VRPTTW × VRPTTW × VRPTTT × VRPTTT × CLRP-DO × VRPD × CSPTW-TN-DO × VRPD × CSPTW-TN-DO × URP × VRPD × URP × VRPD	[35]	2E-VRP			×		Combination of K-means clustering and 2-opt algorithm
Mo-CRPTW-mD × TSP × Mo-CRPTW-mD × TSP × VRPTW × VRPTTW × EVRPTW-RS-SMBS × EVRPTW-LD × CARPTW-LD × CARPSPD-LF × CARPSPD-LF × CARPSPD-LF × CARPW-NC-DO × VRP × CASPTW-TN-DO	[125]	VRP			×		ALNS with an embedded local search
TSP × VRPLTT × × VRPTW × × WRPTW × × VRPTW × × VRPTTW × × VRPTTW × × EVRPSPD-LF × × CIRP-DO × × VRPD × × OMDPDTW-VRP × × VRPD × × CSPTW-TN-DO × × VRPD × × VRPD × × VRPD × × VRPD × × VRPTW × <td>, ;</td> <td></td> <td></td> <td></td> <td></td> <td></td> <td>Abrid multiobjective genetic optimization approach with Pareto local search algorithm. Initial solution</td>	, ;						Abrid multiobjective genetic optimization approach with Pareto local search algorithm. Initial solution
TSP VRPLTT VRP VRPTW TSP VRPTW VRPTW VRPTTW EVRPTW-RS-SMBS EVRPSPD-LIF CARPEDO VRP SE-VRP EVRPSPD-LIF CARP SE-VRP CARP VRP VRP VRP VRP VRP VRP VRP	[74]	Mo-CRPTW-mD			×		is greedy-based heuristic
VRPLTT × × VRPTW-mD × × TSP × × VRPTW × × VRPTW × × EVRPSPD-NL-LD × × VRPD-NL-LD × × VRPD × × VRPD × × VRPD × × VRPD × × URP × × URP × × VRPD × × VRPD × × VRPD × × VRPTW	[8]	TSP			×	×	Hybrid metaheuristic combining ILS and dynamic programming. Branch-and-cut approach
VRP X X TSP X X VRPTW X X VRPTW X X VRPLTT X X EVRPSD-NL- LD X X GLRP-DO X X VRPD X X CSPTW-TN-DO X X URP X X LRP X X URP X X URP X X URP X X URP X X VRPD X X URP X X VRPD X X URP X X VRP X X	[82]	VRPLTT			×		ALNS
Mo-CRPTW-mD × TSP × VRPTW × VRPTTW × 2E-VRP × EVRPSPD-NL-LD × GLRP-DO × VRPD × CSPTW-TN-DO × VRPD × CSPTW-TN-DO × LRP × LRP × VRPD × LRP × VRPD × LRP × VRPD × VRPD × VRPD × VRP × VRP × TSP ×	[83]	VRP		×	×		Concentration-immune algorithm particle swarm optimization (C-IAPSO)
TSP	[74]	Me CDDTW			>		Hybrid multiobjective genetic optimization approach with Pareto local search algorithm. Initial solution
TSP X VRPTW X VRPTW X 2E-VRP X VRPLTT X EVRPSPD-NL- LD X CLRP-DO X VRPD X CSPTW-TN-DO X VRPD X CSPTW-TN-DO X LRP X LRP X VRP X LRP X VRPD X VRPD X VRP X TSP X	[/4]	MO-CKF I W-IIID			<		is greedy-based heuristic
VRPTW × VRPTTW × 2E-VRP × EVRPTW-RS-SMBS × VRPLTT × GLRP-DO × VRP × OMDPDTW-VRP × VRPD × CSPTW-TN-DO × DS-EVRP × LRP × VRP ×	[8]	TSP			×	×	Hybrid metaheuristic combining ILS and dynamic programming. Branch-and-cut approach
VRPTW × 2E-VRP × 2E-VRP × VRPLTT × VRPLTT × GLRP-DO × VRP × CSPTW-VRP × VRPD × CSPTW-TN-DO × DS-EVRP × LRP × LRP × VRP × VRP × VRP × VRP × VRP × VRP × TSP ×	[20]	17.0.077)		spreadsheed-based solution that of
VRPTTW × 2E-VRP × VRPLTT × VRPLTT × GLRP-DO × VRP × CSPTW-TN-DO × VRPD × CSPTW-TN-DO × VRPD × LRP × LRP × LRP × VRPDO × VRPDO × VRPDO × VRPTW × TSP ×	[170]	V KF I W			×		version of the NN heuristic
2E-VRP × EVRPTW-RS-SMBS × VRPLTT × GLRP-DO × VRP × 2E-VRPSPD-LF × OMDPDTW-VRP × VRPD × CSPTW-TN-DO × DS-EVRP × LRP × LRP × VRP × TSP ×	[1]	VRPTTW			×		Simulated annealing (SA) and linear programming
EVRPTW-RS-SMBS × × × × × × × × × × × × × × × × × × ×	[32]	2E-VRP			×		Decomposition algorithm based on the NN heuristic
EVRPTW-RS-SMBS × × VRPLTT × × GLRP-DO × × VRP × × OMDPDTW-VRP × × VRPD × × CSPTW-TN-DO × × LRP × × LRP × × VRP × × TSP × ×	,						Dynamic programming-based heuristic algorithm, exact nondominated paths identification (NDPI)
WRPLTT EVRPSPD-NL- LD	[127]	EVRPTW-RS-SMBS	×		×	×	algorithm, multigraph based DP (MG-DP) combined with DP-based intensified LNS (DP-ILNS) to
VRPLTT × EVRPSPD-NL- LD × GLRP-DO × VRP × OMDPDTW-VRP × VRPD × CSPTW-TN-DO × LRP × LRP × VRP × VRP × VRPDO × VRPTW × VRPTW × TSP ×							obtain a MG-DP-ILNS
EVRPSPD-NL- LD	[82]	VRPLTT			×		ALNS
GLRP-DO	[43]		×		×		MILP and ALNS
VRP 2E-VRPSPD-LF OMDPDTW-VRP VRPD CSPTW-TN-DO DS-EVRP LRP LRP VRP VRP VRP VRP VRP	[20]	GLRP-DO	×				Branch-and-price (B&P)
2E-VRPSPD-LF × OMDPDTW-VRP VRPD CSPTW-TN-DO × × DS-EVRP × LRP VRP VRP VRP VRP VRPDO × × VRP VRP VRP VRP VRP VRP VRP VRP VRP VR	[128]	VRP	×				
OMDPDTW-VRP VRPD CSPTW-TN-DO DS-EVRP LRP LRP VRP VRP VRP VRPDO VRP VRP VRP VRP VRP VRP VRP VR	[30]	2E-VRPSPD-LF	×				
VRPD CSPTW-TN-DO	[129]	OMDPDTW-VRP			×		NN heuristic
CSPTW-TN-DO × DS-EVRP × LRP × VRP × VRPDO × VRP × VRP × VRP × VRP × VRP × VRP × TRP × TSP ×	[92]	VRPD			×		ACO
DS-EVRP	[26]	CSPTW-TN-DO	×		×		ALNS
LRP	[130]	DS-EVRP		×			Safe reinforcement learning method
LRP	[131]	ממו			;		Combination of the progressive hedging algorithm (PHA) and GA. Nondominated sorting genetic
LRP × VRP × 2E-LRP × VRPDO × VRPTW × LRP × TSP × TSP ×	[151]	LKF			×		algorithm II (NSGA-II) and epsilon constraints methods
VRP × 2E-LRP × VRPOO × VRP × VRPTW × LRP × TSP ×	[132]	LRP			×		ALNS using a greedy randomized adaptive search procedure
2E-LRP	[133]	VRP			×		Modified ACO
VRP VRP VRPTW TSP TSP VRPTW X X X X X X X X X	[62]	2E-LRP	×		×		Enhanced hybrid C&W heuristic
VRP × × XX	[27]	VRPDO	×				Branch-and-price-and-cut algorithm
VRPTW × × X TSP × ×	[134]	VRP			×		GA
LRP × × TSP × ×	[135]	VRPTW			×		Genetic simulated annealing algorithm (combination of GA and simulated annealing algorithm)
TSP	[136]	LRP	×		×		NN heuristic and C&W
	[137]	TSP			×		Differential evolution algorithm, GA, particle swarm optimization algorithm (PSO), simulated annealing
							(SA), ACO, artificial fish swarm algorithm (AFSA)

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TABLE A1: Continued.

Reference	Problem	Exact methods	Simulation	Approx algorithm	Dynamic programming	Solution approach
[84]	VRPTW			×		C&W combined with Tabu search (TS)
[138]	FVRP	>				Rearch-and-price-and-cut algorithm
[19]	VRPTWDR	<		×		AINS
[2]	3E-CLRP			× ×		Methods based on continuum approximation (CA) CA-based routing cost estimation (RCF)
[139]	HFVRP-TW			×		LNS
[140]	CVRP		×	×	_	Giant tour best cost crossover operator (GTBCX) employed in a nondominated sorting GA- II (NSGA-II)
	2E-VRPTW-CO-OD			×		ALNS
[142]	SDOVRP			×		GA
[143]	VRP		×	×		Agent-based simulation and discrete event simulation, K-nearest neighbor
[98]	PVRP	×		×		ALNS
[38]	EVRPTW-PR	×		×		VNS, VND
[144]	2E-CMDPVRP			×		Hybrid heuristic with three-dimensional K-means clustering and improved reference point-based
[26]	VPD			>		Based on state-of-the-art machine learning methods in combination with reinforcement learning
[36]	2E-VRP			< ×		Dasce on state-of-ure and unactume rearming memors in communation with reministerness. INS embedded in a heuristic rectangle/cuboid sulitting
[145]	VRPTW		×	<		Survide moons beginning to the month of the
[146]	VRPHLB			×		ALNS and an iterative first-fit decreasing (IFFD) algorithm
[22]	2E-CVRP			×		Parallelized I.NS
[21]	VRPTWDR			: ×		Two-stage mathematic
[147]	VRPDO			×		I.NS in which a set nartitioning problem is periodically used to reassemble routes
						Hybrid immune algorithm (HIA) with the introduction of two improved steps (vaccination and
[28]	2E-LRP			×		immunization)
[148]	LRP			×		TS-modified C&W (TS-MCWS). Sweep-based iterative greedy adaptive LNS (SIGALNS)
[62]	2E-MD-CVRP			×		
[149]	ML-VRPLC			×		Iterative best response algorithm
[62]	LRP			×		C&W
[9]	VRP			×		Agile optimization algorithm that is the combination of biased-randomized heuristics, computer
[0]	ממיזאידים מזים שכ	2		:		paramenzation techniques, and 10.170 techniques
[150]	ZE-EVKFIW-FK	×		× >		ine iuzzy C-mean ciustering C&W
[171]	7F 1 PP		;	< :		Treat to the contract of the c
[7]	ZE-LKF LRP, VRPTW	×	×	×		riatu anu son opunnzanon approacu
[153]	TSP		×	×		Lin-Kernighan heuristic
[154]	VRPTW			×		SNT
[155]	LRP	×		×		MIP-based heuristic
[23]	2E-VRP-CO			×		Tailored adaptive LNS
[156]	MDVRP			×		Biased-randomized techniques integrated with a VNS (BR-VNS)
[157]	2E-LRP			×		Hybrid GA
[158]	VRPMBTW				×	A block nonlinear Gauss-Seidel framework
[159]	VRP			×		ALNS
[160]	VRP-EL			×		SA
[161]	2E-CVRP		×	×		Simheuristic, Monte Carlo simulation, and a decomposition-based heuristic based on MILP
[5]	CVRP	××	>			Branch-and-cut algorithm Dobust ontimization (DO) supersoch A triloged branch and cut hanch and cut and price algorithm
[102]	A IN I W MID	<	<			NOOUSI OPHIIIIZAHOII (INO) APPIOACII. A IAHOICU DIAHCII-AHU-CUI, DIAHCII-AHU-CUI-AHU-PI ICC ABOITUIII

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Table Al: Continued.

15.2 CMDVRPTWA	Reference	Problem	Exact methods	Simulation	Approx algorithm	Approx Dynamic algorithm programming	Solution approach
VRP × CMDVRPTWA × WRP × AVUAVRP × AVUAVRP × VRP × VRPMS × VRPMS × VRPTW × VRPTWP × VRPTW </td <td>[37]</td> <td>EVRP</td> <td></td> <td>×</td> <td>×</td> <td></td> <td>Improved adaptive ant colony algorithm (IACA)</td>	[37]	EVRP		×	×		Improved adaptive ant colony algorithm (IACA)
EVRP VRP AVUANRP 2E-CYRP WRP VRPMS VRPD VRP	[49]	VRP			: ×		Company of the Compan
CMUJVRPTWA VRP AVUAVRP AVUAVRP AVUAVRP AVRP VRP VRP VRP VRP VRP VRP	[47]	FVRP		×	< ×		ACO
AVANRP AVANRP AVANRP AVANRP BE-CYRP VRP VRP VRP VRP VRP SCC-VRP EVRP-ECU SCC-VRP	-	CMDVRDTWA		:	· >		A higherid henristic K-means C&W and an extended nondominated corting GA-II (F-NGGA-II)
AVUAVRP AVUAVRP WRP VRPMS VRPMS VRP VRP VRP VRP VRP VRP VRP VR		VRP			< ×		The hybrid incursate, in the fact of the f
2E-CVRP × WBPVRPD × VRPD × VRPD × VRP × VRPTW × VRP × <td>[165]</td> <td>AVUAVRP</td> <td></td> <td>×</td> <td>×</td> <td></td> <td>Two-phase hybrid heuristic algorithm (TPH) based on TS and GA</td>	[165]	AVUAVRP		×	×		Two-phase hybrid heuristic algorithm (TPH) based on TS and GA
VRP × VRPD × VRPD × VRPD × VRP	[166]	2E-CVRP			×		MILP-based decomposition algorithm
VRP VRPMS VRPM VRP VRP VRP VRP VRP SCE-EVRPTW SCC-VRP EVRP-ECU VRP	[163]	МПРУВРВ			>		A hybrid heuristic algorithm incorporating a 3D clustering and an improved multiobjective particle
VRPMS × VRPD × VRP VRP × VRP VRP × VRP VRP × VRP	[102]	MIDI VINI I D			<		swarm optimization (IMOPSO)
VRPMS × VRPD × VRPTW × VRP × VRPTW × VRPTW × VRPTW × VRP × VRP <td>[99]</td> <td>VRP</td> <td></td> <td></td> <td>×</td> <td></td> <td>TOPSIS (multicriteria decision-making) and multiobjective MILP</td>	[99]	VRP			×		TOPSIS (multicriteria decision-making) and multiobjective MILP
VRPD × VRPTW × VRP × VRP × SCC-VRP × EVRP-ECU × VRP × VRPTW × LRP × EVRPTW × VRPTW × VRPTW × VRP ×	[167]	VRPMS	×		×		GA
VRPTW VRP VRP VRP SCE-VRP EVRP-ECU VRP VRP VRP VRPTW SE-EVRP SE-EVRP SCE-VRP SCE-VRP SCE-VRP SCE-VRP SCE-VRP SCE-VRP SCE-VRP SE-EVRP SE-VRP	[62]	VRPD	×				
VRP × × VRP × × SCC-VRP × × EVRP-ECU × × VRP × × VRPTW × × LRP × × EVRPST × × VRPTW × × VRP × ×	[168]	VRPTW			×		Mixed-integer linear programming (MILP)
VRP × VRP × SCC-VRP × EVRP-ECU × VRP × VRPTW × LRP × EVRPST × VRPTW × VRPTW × VRP × VRP <t< td=""><td>[75]</td><td>VRP</td><td></td><td>×</td><td>×</td><td></td><td>Lin-Kernighan heuristic</td></t<>	[75]	VRP		×	×		Lin-Kernighan heuristic
2E-EVRPTW-BSS × VRP × SCC-VRP × EVRP-ECU × VRP × VRPTW × LRP × EVRPST × VRPTW × VRPTW × VRP × VRP × VRP × TDVRPCHF × VRP × TDVRPCHF × VRP × <		VRP	×				Linear programming
VRP × SCC-VRP × FVRP-ECU × VRP × VRPTW × LRP × EVRPST × VRPTW × VRPTW × VRP × VRP × TDVRPCHF × VRP × TBVRPCHF × VRP × VRP <td></td> <td>E-EVRPTW-BSS</td> <td>×</td> <td></td> <td></td> <td></td> <td></td>		E-EVRPTW-BSS	×				
SCC-VRP EVRP-ECU VRP VRP VRPTW 2E-EVRP 2E-EVRP 2E-EVRP LRP LRP LRP EVRPST VRPTW VRP VRP TDVRPCHF VRP TDVRPCHF VRP VRP TDVRPCHF VRP VRP VRP TDVRPCHF VRP VRP VRP VRP TDVRPCHF VRP VRP VRP VRP VRP VRP VRP VR	[171]	VRP		×	×		Deep reinforcement learning algorithm
EVRP-ECU	[172]	SCC-VRP			×		Hybridized GRASPxILS metaheuristic
VRP × VRPTW × 2E-EVRP × 2E-EVRP-BSS × 2E-TVRP × LRP × EVRPST × VRP × VRP × VRP × VRP × TDVRPCHF × VRP	[47]	EVRP-ECU	×		×		Robust optimization techniques. Heuristics based on LNS
VRPTW × 2E-EVRP × 2E-EVRP-BSS × 2E-TVRP × LRP × EVRPTW × VRP	[38]	VRP			×		Evolutionary algorithms
2E-EVRP × 2E-EVRP-BSS × 2E-TVRP × LRP × EVRPTW × VRP <	[40]	VRPTW			×		SZS
2E-EVRP-BSS × 2E-TVRP × LRP × EVRPST × VRP VRP × VRP × VRP × VRP × TDVRPCHF × VRP × VRPSPD-D2D × VRP × VRP<	[24]	2E-EVRP	×		×		INS
2E-TVRP × LRP × VRPTW × VRP × VRP × VRP × VRP × TDVRPCHF × VRP × VRP × VRPSPD-D2D × VRP × VRP <t< td=""><td>[17]</td><td>2E-EVRP-BSS</td><td></td><td></td><td>×</td><td></td><td>Hybrid algorithm that combines a column generation and an ALNS (CG-ALNS)</td></t<>	[17]	2E-EVRP-BSS			×		Hybrid algorithm that combines a column generation and an ALNS (CG-ALNS)
LRP VRPTW X VRP X VRP X VRP X VRP X TDVRPCHF X VRP X HFVRP, VRPPC, X 2E-VRP X VRP X VRP X VRP X 2E-VRP X 2E-VRP X 2E-CLRP X	[173]	2E-TVRP			×		Savings-based algorithm followed by the VNS
EVRPST × VRPTW × VRP × VRP × TSP × VRP × TDVRPCHF × VRP × HFVRP, VRPPC, × 2E-VRP × VRP × VRP × VRP × VRP × VRP × 2E-VRP × 2E-VRP × 2E-CLRP ×	[54]	LRP					
VRPTW × VRP × VRP × VRP × VRP × HFVRP, VRPPC, × 2E-VRP × VRP × VRP × VRP × VRP × 2E-VRP × VRP × 2E-VRP × 2E-VRP × 2E-CLRP ×	[6]	EVRPST		×	×		Simheuristic, Monte Carlo simulation with a multistart metaheuristic and with biased-randomization
VRPTW	[174]	VRPTW			>		techniques Henristic based on scatter search
VRP	[38]	VP DTW			< >		Manastr of annie search
VRP TSP VRP VRP TDVRPCHF VRP VRP HFVRP, VRPPC, 2E-VRP VRP VRP VRP VRP VRP VRP VRP VRP VRP	[91]	VRP	×		<		MATTERIA ARGOLUTIONI
TSP	[175]	VRD	(>	>		I ANTIME metaborrietic (commisse II insertion bourietic nerallal insertion bourietic DI and TC)
VRP TDVRPCHF VRP HFVRP, VRPPC, 2E-VRP VRPPPDD2D VRP VRP VRP VRP VRP SE-VRP 2E-VRP X 2E-VRP X X X X X X X X X X X X X	[67]	TSP		<	× ×	×	Language in the first interest of the first first first for the control of the first interest in the first interest in the first interest in the first interest in the first interest interest in the first interest intere
TDVRPCHF × × × WRP + FVRP, VRPPC, 2E-VRP	[28]	VRP			×		8
VRP × × HFVRP, VRPPC, × 2E-VRP × VRP × VRP × VRP × 2E-VRP × 2E-CLRP ×	[176]	TDVRPCHF			×		Simplified swarm optimization algorithm
HFVRP, VRPPC, 2E-VRP VRPSPD-D2D VRP VRP VRP X 2E-VRP X 2E-CLRP X	[177]	VRP		×	×		C&W for initial solutions and then TS
VRPSPD-D2D × VRP × VRP × 2E-VRP × 2E-CLRP ×		IFVRP, VRPPC, 2E-VRP			×		ACO
VRP × VRP × 2E-VRP × 2E-CLRP ×	[178]	VRPSPD-D2D			×		Two honey bee-inspired metaheuristics: artificial bee colony (ABC) at the first stage; bee colony
VRP × 2E-VRP × 2E-CLRP ×		0.071			:		optimization (BCO) at the second stage $\frac{1}{2}$
J 2E-VRP × × 2E-CLRP × ×	[1/9]	VRP			× ;		Hybrid evolutionary VND, combining the GA with a VND C_{outing}
2E-CLRP ×	[20] [176]	ZE-VRP			< ×		CONTINUOUS APPIOAMMANON (CA) MOUSI ALNS
ZB-CLINT ×	[24]	JE CI DD			>		Cooperative approximation heuristic algorithm (facility-location phase with a Lagrangian relaxation
	[34]	ZE-CLNF			×		approach, routing phase by a granular TS)

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Table A1: Continued

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TABLE A2: Classification of performance indicators for each document analyzed.

			nmental		ogistics		,		A1
Article	Use of resources	Emissions	Transportation modes	Infrastructure	Productivity	Time	Social	Economic	Algorithm performance
[33]	×	×	×		×		×	×	
[35]								×	
[96]		×			×			×	
[57]					×			×	
[32] [43]		×	×		×				
[29]			×			×		×	×
[128]		×						×	^
[30]	×				×			×	×
[76]			×	×	×			×	×
[59]				×			×	×	
[130]	×		×						
[131]		×						×	
[125]								×	
[126]			×			×		×	
[1] [127]	×	×	×		×	×		×	
[83]	^	^	^		^			×	
[74]							×	×	
[8]					×				×
[82]	×		×		×				
[132]			×		×			×	
[133]		×						×	
[97]								×	
[27]								×	
[134]			×	×	×				
[135] [136]					×			×	
[130]					×				×
[84]					×			×	×
[138]								×	
[19]						×			
[2]								×	
[139]					×			×	
[140]					×				
[141]								×	
[142] [216]			× ×					×	
[143]		×	×	×	×			^	
[86]		^	^	^	^			×	×
[39]			×			×			×
[216]			×			×		×	×
[56]						×			
[81]		×					×	×	
[145]		×			×	×			
[146]		.,	×	×				×	
[77] [19]		×				×		×	
[79]		×	×	×		×			
[147]		^	^	^		^		×	
[58]		×						×	
[148]								×	
[95]		×	×					×	
[149]									×
[6]		×	×		×	×			
[150]								×	
[217]								×	
[151]					~			×	
[7]					×				

Table A2: Continued.

		Enviro	nmental	L	ogistics				A1
Article	Use of resources	Emissions	Transportation modes	Infrastructure	Productivity	Time	Social	Economic	Algorithm performance
[152]					×			×	
[153]		×					×	×	
[155]								×	
[23]			×	×	×			×	
[156]		×			×	×	×		
[157]			×		×			×	
[158] [159]	~		~					×	×
[160]	×	×	×		~			×	×
[160]	^	^	× ×		×				×
[5]			^		^	×			×
[162]						^		×	×
[64]									
[37]	×		×		×	×		×	×
[49]			×		×	×			
[65]		×			×		×	×	
[218]			×					×	
[164]	×	×	×						
[165]								×	
[166]			×	×	×				
[163]			×			×		×	
[66]		×						×	
[167]								×	
[62]		×	×					×	
[168]			×		×			×	
[75]	×		×			×			
[169]	×	×	×					×	
[170] [171]	×		×		~			×	
[171]					×			×	×
[47]	×		×					×	^
[38]	^		×		×			^	
[24]			•					×	
[17]		×						×	×
[173]	×		×					×	×
[54]								×	
[9]					×				
[174]			×		×				
[40]			×		×				
[91]								×	
[175]			×			×			
[67]				×					×
[178]			×					×	
[179]			×		×			×	
[78]									
[176]					×		.,		×
[177] [88]		~			×		×	~	
[20]		× ×						× ×	
[20]		^	×	×				×	
[34]		×	×	^	×			×	
[93]		•	^					×	
[213]					×			×	×
[181]			×		. •			×	
[182]							×	×	
[183]								×	×
[184]					×			×	
[185]								×	×

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TABLE A2: Continued.

		Enviro	nmental	L	ogistics				Algorithm
Article	Use of resources	Emissions	Transportation modes	Infrastructure	Productivity	Time	Social	Economic	performance
[186]		×	×			×		×	
[187]	×	×	×		×	×			
[188]			×		×			×	
[189]		×	×	×	×		×	×	
[190]					×			×	
[191]		×				×		×	
[192]		×	×						×
[41]			×	×				×	
[28]				×				×	×
[25]					×				×
[193]								×	×
[194]			×		×	×		×	
[52]			×		×				
[195]			×		×			×	
[196]		×			×			×	
[197]	×		×		×			×	×
[198]	×		×		×				
[200]	×	×	×						
[18]			×	×					
[201]			×	×					
[202]	×	×	×	×					
[203]			×						
[204]		×	×						
[205]	×	×	×						
[22]	×		×						
[206]				×					
[42]	×			×					
[207]	×			×					
[208]			×		×				
[16]		×		×					
[209]			×	×					
[210]		×	×						
[220]		×	×						
[211]		×	×						
[31]				×					

Data Availability Statement

All analysis data concerning the articles in this systematic literature review are available in the Appendix.

Disclosure

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Conflicts of Interest

The authors declare no conflicts of interest.

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