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Wetting of hydrophilic electrospun mats produced by blending SEBS with PEO-PPO-PEO copolymers of different molecular weight

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ABSTRACT: The interaction of electrospun mats with water is critical for many possible applications, and the water contact angle on the surface is the parameter usually measured to characterize wetting. Although useful for hydrophobic surfaces, this approach is limited for hydrophilic mats, where wicking has also to be considered. In this case, it is still unclear how the fiber surface chemical composition and morphology will affect the wetting behavior of electrospun mats. In this work, wetting was studied with different hydrophilic membranes produced by blending thermoplastic elastomer SEBS with amphiphilic PEO-PPO-PEO molecules. Three different types of PEO-PPO-PEO, with different molar masses, PEO content and physical form were used. The effect of these differences on the wetting behavior of the electrospun mats was evaluated by contact angle goniometry, wicking measurements and

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3 different imaging techniques. X-ray photoelectron spectroscopy was used to characterize the
4 surface chemical composition. The smaller molecules quickly saturated the surface at low
5 concentrations, making the mats hydrophilic. The sheath of PEO-PPO-PEO also resulted in fast
6 absorption of water, when comparing the saturated and non-saturated surfaces. Longer PEO
7 chain-ends seemed to hinder complete segregation and also led to a higher activation time when
8 in contact with water. Liquid PEO-PPO-PEO was easily leached by water.
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22 INTRODUCTION

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24 High surface area is one of the main features of electrospun mats and therefore understanding
25 and controlling their surface properties is critical. Water wetting, for example, will help defining
26 the performance of mats for several possible applications where there is interaction with aqueous
27 solutions, such as separation and filtration membranes or scaffolds for tissue engineering^{1, 2, 3}.
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33 Electrospun mats are generally classified as hydrophobic or hydrophilic. In the case of many
34 polymers^{4, 5, 6, 7}, the mats produced by electrospinning are hydrophobic and need to undergo a
35 post-treatment in order to present hydrophilicity. This can be achieved by hydrolysis^{4, 5}, plasma⁸,
36 immersion precipitation⁹, etc., but this adds time and cost. Another approach is to use polymer
37 blending to incorporate hydrophilic¹⁰ or amphiphilic^{11, 12} polymers in the hydrophobic matrix to
38 alter the surface properties of the fibers. Previously¹³, we have shown that mats of elastomeric
39 poly(styrene)-*b*-poly(ethylene-butylene)-*b*-poly(styrene) (SEBS) could be hydrophilized by
40 blending it with amphiphilic poly(ethylene oxide)-*b*-poly(propylene oxide)-*b*-poly(ethylene
41 oxide) (PEO-PPO-PEO). Not only the chemical composition but also the blend morphology was
42 important to produce a homogeneously hydrophilic mat. The low surface energy PPO midblock
43 tends to segregate to the surface and drag the hydrophilic PEO groups. When in contact with an
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3 aqueous medium, the hydrophilic PEO segments will extend and the surface will become
4 hydrophilic¹⁴. There exist other examples in literature where PEO-PPO-PEO polymers have been
5
6 successfully used to modify the wettability of the electrospun mats^{11, 12}, but to our knowledge the
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8 characterization of wetting was based only in static contact angle measurements.
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12 In the hydrophobic case, electrospun mats can be seen as a rough surface, and many papers in
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14 the literature have discussed the reasons and definitions for hydrophobicity based on contact
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16 angle measurements and wetting theories^{15, 16}. In the hydrophilic case, however, electrospun mats
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18 cannot be seen only as a rough surface, but also as a porous material subject to absorption by
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20 capillary action (wicking). So to better understand the wetting behavior of hydrophilic
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22 electrospun mats, not only contact angle but also wicking measurements have to be analyzed.
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24 The latter have been used to determine the contact angle of electrospun mats indirectly⁵, or to
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26 compare the wicking rate of spunbond and electrospun fibers⁷, mats of the same polymer with
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28 different fiber diameter⁶ or mats containing two types of fibers independently co-electrospun⁴.
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30 Another way used to characterize the dynamics of wetting is the observation of the spontaneous
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32 spreading or impact of droplets^{17, 18}, which can also be important for applications in humid
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34 conditions or related to the deposition of aqueous fluids. However, it is still unclear how the fiber
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36 surface chemistry and morphology will affect wetting of electrospun mats.
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43 Since there are many different grades of PEO-PPO-PEO copolymers commercially available,
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45 combining hydrophilization by blending with different types of PEO-PPO-PEO and analyzing
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47 contact angle, wicking rate, spreading and impact of water on the mats can give new information
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49 about the role of fiber surface composition and morphology on the wetting behavior of
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51 electrospun mats. In this work, SEBS/PEO-PPO-PEO mats were produced by electrospinning
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53 with three types of PEO-PPO-PEO molecules having different molar masses, PEO content and
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physical form (one is a solid polymer, the other a paste-like material and the last one a viscous liquid). The effect of these differences on the wetting behavior of the mats was evaluated by contact angle, wicking measurements and imaging techniques. Surface chemical composition and both mat and fiber morphology were also characterized.

EXPERIMENTAL

Linear triblock copolymer SEBS (G1652) with 79 000 g/mol of average molecular weight and 30 wt% of styrene blocks was kindly supplied by Kraton. PEO-PPO-PEO copolymers (Pluronic[®]) were purchased from Sigma Aldrich. Chloroform and toluene were purchased from Fisher Scientific. Three types of PEO-PPO-PEO copolymers were used: Pluronic[®] F127, Pluronic[®] P123 and Pluronic[®] L61, each with different molecular weight and PEO content. The main characteristics are presented in Table 1 with a visual comparison using an arbitrary scale of the difference in length and PEO content in each polymer with the respective number of EO and PO repeat units.

Table 1 - Main features of the PEO-PPO-PEO copolymers used in the present study.

Polymer	F127	P123	L61
Molecular weight (g/mol)	12 600	5 800	2 000
wt% of PEO	73.2	30.0	10.0
Physical form	Flakes	Paste	Liquid
Comparative sketch			

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3 The polymers were weighed and mixed with chloroform and toluene (80/20 wt%) using a
4 magnetic stirrer for 15 minutes until a homogeneous solution was obtained. The final polymer
5 concentration for all solutions was 15 wt%. Four compositions of SEBS/PEO-PPO-PEO with 5,
6 10, 15 and 20 wt% of each PEO-PPO-PEO were prepared and named as F127_x, P123_x and
7 L61_x, where x is the wt% of PEO-PPO-PEO.
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15 Electrospinning was performed with 10 ml syringes, 21G needles, voltage of 15 kV, distance
16 to collector of 15 cm and flow rate of 2 mL/h. All the tests were performed at room temperature
17 and 30 % of relative humidity.
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22 Water contact angle measurements were performed with a VCA Optima (AST products, Inc.)
23 and Milli-Q[®] ultrapure water. Mat strips were attached to glass slides to maintain a horizontal
24 surface. Each blend was tested five times in different regions of the mats.
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29 For the wicking measurements, ultrapure water was dyed with methylene blue and poured in a
30 beaker. Mat strips with 20 mm of height, 10 mm of width and 150-200 μm of thickness were
31 attached to a polyethylene tab containing a millimetric scale. The tab was lowered until the
32 solution touched the mat and the water started to rise by capillary action. All the process was
33 recorded with a Canon T4i at thirty frames per second. The time to reach each millimeter in the
34 scale was then plotted in a height vs. time graph. Three samples of each composition were tested.
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44 Optical microscopy was performed with an Olympus BX51 with magnification up to 1000 \times to
45 observe the fiber morphology and leaching. Scanning electron microscopy (SEM) was used to
46 observe both the mat morphology (fiber diameter and shape) and fiber surface morphology. The
47 experiments were performed with a S3600N microscope (Hitachi) at 5kV in secondary electrons
48 mode. The samples were previously coated with platinum using a Q150T S (Quorum
49 Technologies) sputter coater. High-speed images of wetting were obtained using a Fastcam SA1
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3 Camera (Photron Ltd, Tokyo, Japan) working at 500 to 2000 frames per second depending on the
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5 absorption velocity of each sample. This technique was used to analyze the dynamics of
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7 spreading and impact of water drops on the mat surfaces. All images were analyzed using ImageJ
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9 and the plugin DiameterJ¹⁹ for measurements.
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13 The surface chemical composition of the samples was measured by X-ray Photoelectron
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15 Spectroscopy (XPS) using an ESCALAB 3 MKII with a Mg K α source and 216W (12 kV, 18
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17 mA) of power. An area of 2 mm \times 3 mm was analyzed for each sample, with a depth of analysis
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19 of 50 - 100 Å.
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24 25 RESULTS AND DISCUSSION

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27 Figure 1 shows the water contact angle results for each blend as a function of PEO-PPO-PEO
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29 bulk content for the three types of PEO-PPO-PEO (F127, P123 and L61). Pure SEBS mats were
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31 hydrophobic with contact angle of $139 \pm 2^\circ$. For the blends containing F127, the hydrophilization
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33 (absorption resulting in contact angle of 0°) was achieved at 15 wt% of PEO-PPO-PEO, but only
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35 the composition with 20 wt% presented a homogeneous hydrophilicity in all regions of the mat.
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37 The addition of 5 wt% P123 or L61 was enough to hydrophilize the mats. Blends with only 1
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39 wt% of P123 and L61 were later prepared, producing hydrophobic mats with contact angle closer
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41 to pure SEBS ($\approx 140^\circ$).
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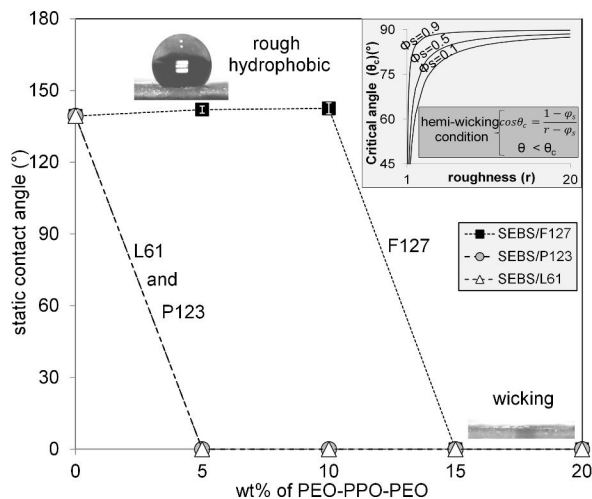


Figure 1 – Water contact angle results for all electrospun mats as a function of PEO-PPO-PEO content. The insert is a plot of the hemi-wicking condition²⁰, the critical contact angle θ_c as a function of roughness r for different values of solid/liquid interface fraction (ϕ_s).

The condition for wicking in a perfect capillary is that the surface energy between the solid and the liquid (γ_{SL}) must be smaller than the surface energy between the solid and the air/vapour (γ_{SV}). Using the equilibrium contact angle θ_E of the Young's equation ($\gamma_{SV} - \gamma_{SL} = \gamma_{LV} \cos \theta_E$), which describes the balance of energies for a drop of liquid deposited in a perfectly flat surface, the condition for wicking may be written as²¹ $\theta_E < 90^\circ$ that gives $\gamma_{SV} - \gamma_{SL} > 0$.

Electrospun mats can be considered as non-perfect porous structures in which the solid/vapour interface will not be ideally replaced by a solid/liquid interface, leaving some dry islands. The condition for wicking or hemi-wicking can be described as²⁰:

$$\theta_E < \theta_c \text{ and } \cos \theta_c = \frac{1 - \phi_s}{r - \phi_s}$$

where r is the roughness (ratio of the real area to the projected area), ϕ_s is the fraction of the solid/liquid interface below the drop, θ_E is again the equilibrium contact angle on an ideal flat surface with the same chemical composition of the rough surface and θ_c is the critical contact

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3 angle that will define the start of the imbibition²⁰. For a perfect porous material ($r \rightarrow \infty$ and
4 therefore $\cos\theta_c \rightarrow 0$), wicking will occur again for $\theta_E < 90^\circ$ and, if this condition is fulfilled, the
5 final apparent contact angle will be 0° . Considering that electrospun mats are porous materials
6 with high values of roughness, the condition for imbibition is easily achieved, and for any value
7 of ϕ_s , θ_c tends to be close to 90° , as shown in the insert in Figure 1. This explains the recurrent
8 switch (ON/OFF) mechanism found for the contact angle of electrospun mats, from hydrophobic
9 or superhydrophobic rough surfaces with high contact angle values to superhydrophilic
10 absorbing porous structures with contact angle zero^{10, 12, 22, 23, 24}.

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13 Mats that present values of contact angle smaller than 90° but higher than 0° can be a result of:
14 non-uniform chemical composition, with hydrophobic regions unevenly mixed with hydrophilic
15 regions; small mat thickness with insufficient pore volume to absorb the droplet; measurement at
16 different times, as some mats present a slow wicking rate until the contact angle reaches zero.
17 The contact angle right after the droplet deposition may be different from zero and then reach
18 zero after a time interval¹². In the case of this work, the absorption occurred rapidly after the
19 drop deposition.

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22 The contact angle measurement was useful to determine the effectiveness of the
23 hydrophilization treatment chosen, i.e., blending with PEO-PPO-PEO molecules, but it did not
24 allow a comparison between the different hydrophilic compositions. To investigate the dynamics
25 of spreading and imbibition from the moment the drop touched the mat until it was completely
26 absorbed, high-speed imaging was used (Figure 2). Four compositions were chosen for clarity
27 and because they summarize the main trends observed. The evolution of the contact angle θ of
28 the droplet on the surface was observed as a function of time (Figure 2a). Upon contact, all mats
29 presented contact angles around 140° , which is similar to the values obtained for pure SEBS and
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for the hydrophobic blends. Given the difference in time scale for the complete absorption, the curve for the F127_20 mat was included as an insert. Contact angle values decreased with a higher rate until around 800 milliseconds (0.8 seconds) for the F127_20 and around 50 milliseconds (0.05 seconds) for the P123_20, L61_5 and L61_20. A second regime with a lower decrease rate took place after that, at around 20-30°, for all the mats. The contact angle continued to decline until complete absorption of the droplet at around 2000 milliseconds (2 seconds) for the F127_20, 200 milliseconds for the P123_20 and 80-90 milliseconds for the blends with L61, which presented similar behavior for all parameters. Besides the differences in order of magnitude the spreading behavior was analogous for the mats tested.

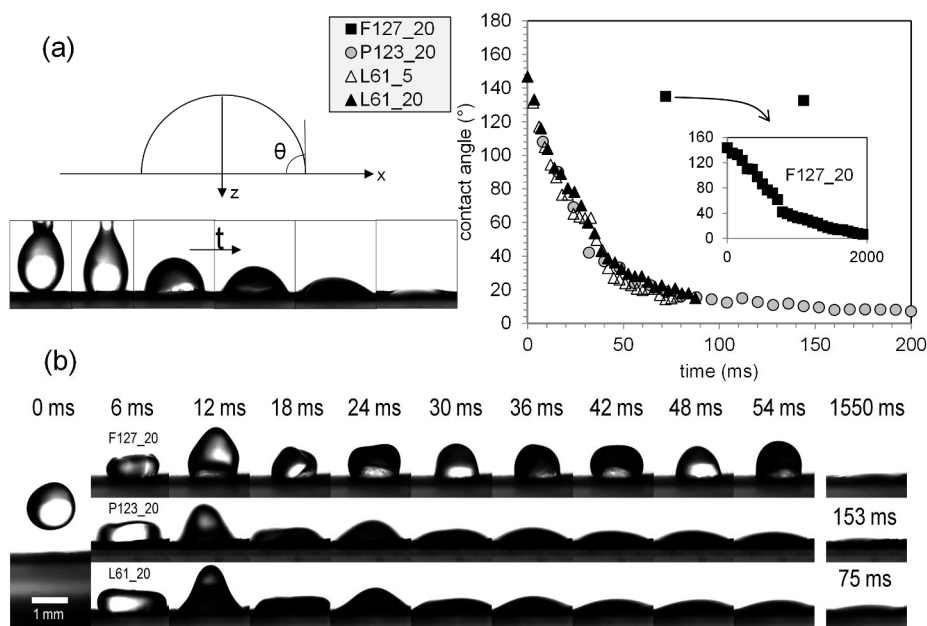


Figure 2 – (a) spreading and imbibition experiments methodology and results for the contact angle θ as a function of time; (b) drop impact images showing the last frame before impact as the first image and the total time for absorption as the final image for F127_20, P123_20 and L61_20 (top to bottom).

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6 The differences in drop absorption between F127_20, P123_20 and L61_20 were also
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8 observed in drop impact experiments (Figure 2b). For the F127_20 mat, there was no apparent
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10 change in volume and contact angle in the early stages after the impact, and droplet moved up
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12 and down for a longer time without bouncing. In the case of P123_20 and L61_20, the droplet
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14 adhered and moved on the surfaces while it was rapidly absorbed. As concluded by the spreading
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16 experiments, there was a drastic difference between the behavior of F127_20 and the P123_20
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18 and L61_20. Also, the impact reduced the final absorption time by about 20 %. The pictures
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20 presented in Figure 2b also show that in all cases the drop adhered to the surface and no
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22 splashing was observed.
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27 One way to predict the impact behavior of a liquid drop on a surface is to calculate the
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29 dimensionless Weber number ($We = \rho r v^2 / \gamma$), where ρ is the liquid density, r the drop radius, v its
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31 impact velocity and γ the surface tension. A rough evaluation of the Weber number for the
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33 present work ($\rho = 1000 \text{ kg.m}^{-3}$, $r = 650 \text{ }\mu\text{m}$, $v = 0.3 \text{ m.s}^{-1}$ and $\gamma = 72 \text{ mN.m}^{-1}$) leads to $We = 8.2$,
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35 which is much lower than the splashing thresholds usually reported^{25, 26, 27}, even considering that
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37 the roughness can reduce this limit²⁸, explaining therefore the absence of splashing in our work.
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39 Furthermore, hydrophilic surfaces cause a much stronger viscous dissipation near the moving
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41 contact line that slows down the droplet spreading, in contrast to hydrophobic surfaces²⁶, which
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43 can also contribute to avoid splashing. However, it is worth noting that a small increase in the
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45 drop velocity drastically changes the impact behavior, and that even hydrophobic electrospun
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47 membranes can be penetrated by water if the velocity is high enough^{29, 30}. Lembach et. al³⁰ also
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49 performed drop impact experiments on electrospun mats produced with a partially wetttable
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51 polymer, and defined a splashing threshold for these mats. To reach this threshold with the mats
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3 used in the present work, a velocity of 2.7 m/s would be necessary (much higher than the one
4 used in the present work).
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8 Wicking experiments with mat strips were performed to evaluate another aspect of the wetting
9 behavior³¹ of electrospun materials. The results are presented in Figure 3a for the hydrophilic
10 compositions from the moment the dyed water touched the mat until it reached the sample height
11 of 20 mm, as shown by the pictures in Figure 3a. Although ultimately hydrophilic in terms of
12 contact angle, the strips of the composition with 15 wt% of F127 presented heterogeneous water
13 rise with time so that the results are not shown here. The dyed water had a preference for the
14 more hydrophilic regions, which were randomly distributed in the mats. Controlling the exact
15 location of hydrophobic and hydrophilic regions could lead to a tailored wicking behavior that
16 could be interesting for applications involving fluid transport.
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29 The wicking rate was clearly smaller for the mat with 20 wt% of F127, and the time to reach
30 the maximum height was about 17 seconds. All the mats with P123 quickly absorbed water with
31 a total time between 5 and 8 seconds. The wicking rate for the mats with L61 was even higher
32 with total time between 4 and 6 seconds to reach the maximum height.
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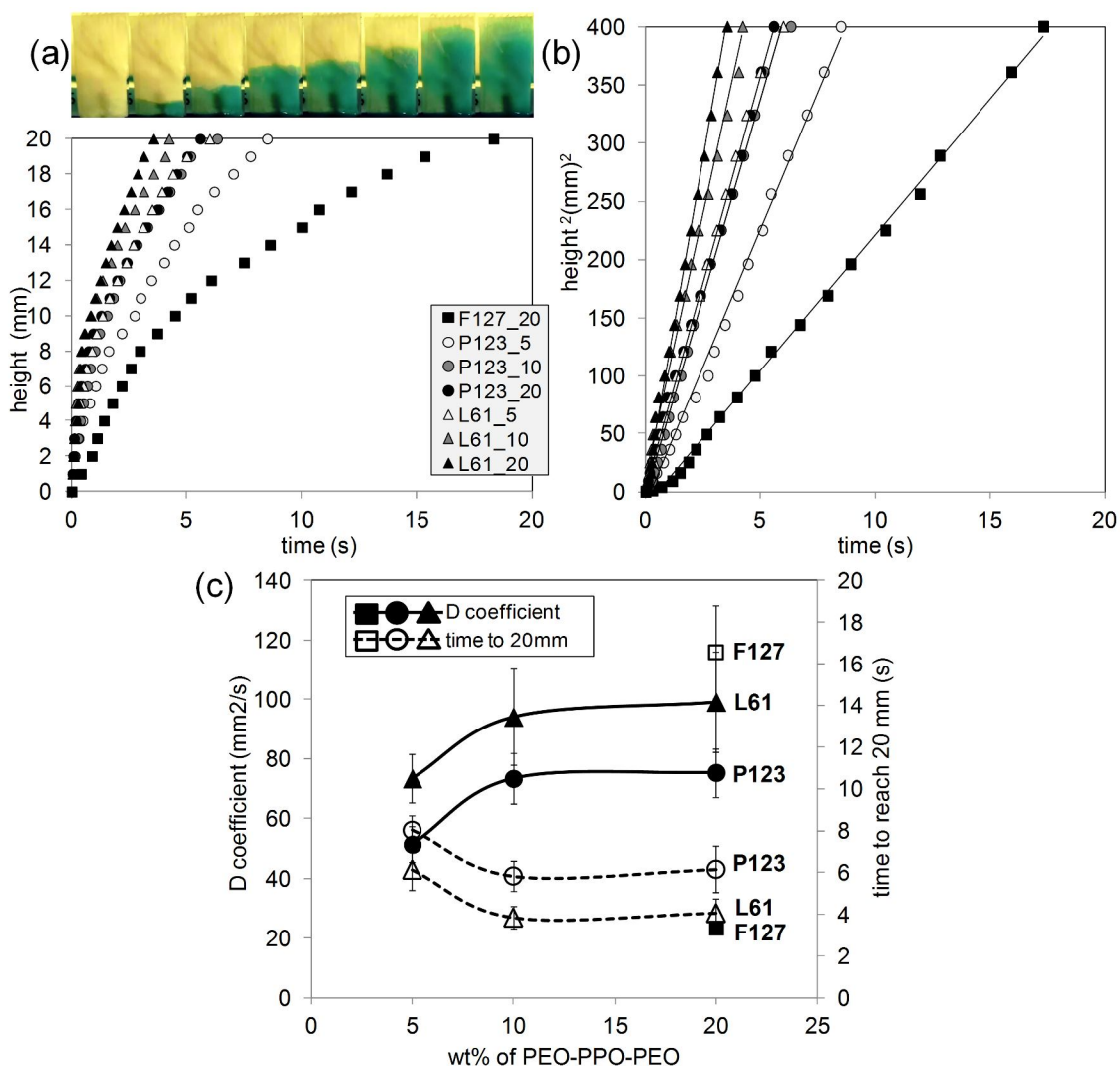


Figure 3 – Results for the wicking measurements: (a) example of the experiments pictures and the results for height as a function of time; (b) the square of height (h^2) versus time; (c) Diffusion coefficient D and total time to reach the maximum height as a function of PEO-PPO-PEO content.

Porous materials like electrospun mats can exhibit classical wicking dynamics analogous to what was described by Washburn³² considering a porous structure as a series of n cylindrical

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3 capillaries with an equivalent radius of the capillary structure r . Neglecting the hydrostatic
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5 pressure, the relation between the height h and time t can be described as³³:
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$$8 \quad h^2 = \left(\frac{r \cdot \cos\theta_E}{2} \right) \cdot \left(\frac{\gamma}{\eta} \right) \cdot t$$

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11 where γ and η correspond to the surface tension and viscosity of the liquid. The rise of liquid in
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13 a capillary then takes the form:
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$$15 \quad h^2 = D \cdot t$$

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17 where D is a diffusion coefficient based on fluid properties and capillary geometry, and the
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19 square of the height varies linearly with time. Figure 3b shows that the equation fitted well to the
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21 wicking behavior of electrospun mats considering the whole experiment, as previously reported⁶,
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7. The differences in wicking rate described before are easier to observe.

Figure 3c presents the D coefficient and time to reach the maximum height as a function of PEO-PPO-PEO content for all the compositions and samples tested. The time to reach the maximum height of 20 mm, a parameter used in many wicking standards, decreased with higher PEO-PPO-PEO content, but reached a plateau around 10 wt%. The D coefficient followed the inverse trend, increasing with PEO-PPO-PEO content, but also stabilizing after 10 wt%.

Since $D = (r \cdot \cos\theta_E/2) \cdot (\gamma/\eta)$ and only water was used in the experiments (constant γ and η), any difference in the wetting behavior comes from differences on the pore structure or the surface chemical composition.

The main structure parameters that will affect wicking in a simplified electrospun mat (Insert in Figure 4b) are the fiber diameter d and the distance between fibers f , which will influence pore (capillary) size. SEM images for some of the samples are presented in Figure 4a, showing that all compositions produced homogeneous fibers with the exception of P123_20, which presented fibers with varying diameter, and L61_20, which presented broken fibers. Fiber diameter

decreased drastically with the incorporation of 5 wt% of all three types of PEO-PPO-PEO molecules, and remained stable until the maximum concentration of 20wt% (Figure 4b) The only exceptions are again P123_20 and L61 20, which presented an increase in the average diameter (Figure 4b). The higher amount of PEO-PPO-PEO started to disrupt the electrospinning process in these two cases. Image analysis was performed to calculate the distance between fibers and the pore size of the mats, but the data (not presented here) revealed, as expected, a great variation since the mats are composed of randomly oriented fibers. However, it is known that mats containing fibers of smaller diameter have smaller pores³⁴, so that one could expect smaller pores for the blends containing F127 and therefore smaller capillaries that would increase the wicking rate, but that was not observed. The total porosity value taken from immersion experiments in ethanol revealed similar values for all mats (around 75%). Therefore, based on this simple analysis, there is no apparent correlation between geometry and the wetting behavior of the mats.

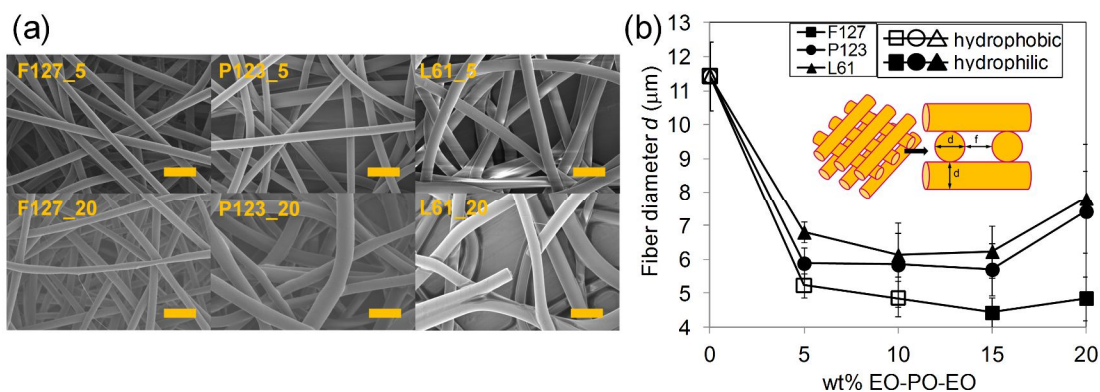


Figure 4 – (a) SEM micrographs of the samples containing 5 and 20 wt% of PEO-PPO-PEO (scale bar = 20 μm) and (b) the results of fiber diameter as a function of PEO-PPO-PEO content for all samples.

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3 The chemical composition at the very top surface of the mats, measured by XPS, is presented
4 in Figure 5. Since only the PEO-PPO-PEO molecules have oxygen, the atomic percentage of this
5 element can tell whether the surface is enriched with this polymer or not. Figure 5a shows the
6 XPS survey spectra for pure SEBS, the three blends containing 20 wt% of PEO-PPO-PEO and a
7 film of pure PEO-PPO-PEO (P123). The small oxygen peak in the spectrum of pure SEBS,
8 combined with a small silicon peak, appeared possibly due to a small amount of silicone oils that
9 can be found in some commercial polymers. The spectra for P123_20, L61_20 and pure PEO-
10 PPO-PEO (P123) presented similar proportion between carbon and oxygen peaks, although the
11 sample for pure PEO-PPO-PEO was a film, since it is not electrospinnable. The curves in Figure
12 5b show the atomic percentage of oxygen for each composition. From bottom to top, the straight
13 lines without markers show the theoretical amount of oxygen expected according to the bulk
14 compositions and the theoretical amount of oxygen in pure L61, P123 and F127, respectively.
15 All compositions presented surface enrichment with PEO-PPO-PEO, which confirms that there
16 was segregation of these molecules. For the blends with F127 there was a gradual increase in the
17 amount of oxygen according to the composition. Blends with P123 showed an instant high
18 amount of oxygen at 5 wt% of P123, similar to the blend with 20 wt% of F127. From 10 until 20
19 wt% of P123, the surface is practically saturated (91 to 100 wt%) with PEO-PPO-PEO
20 molecules. When L61 was use as the second phase, all compositions tested presented completely
21 coverage with the amphiphilic molecule.
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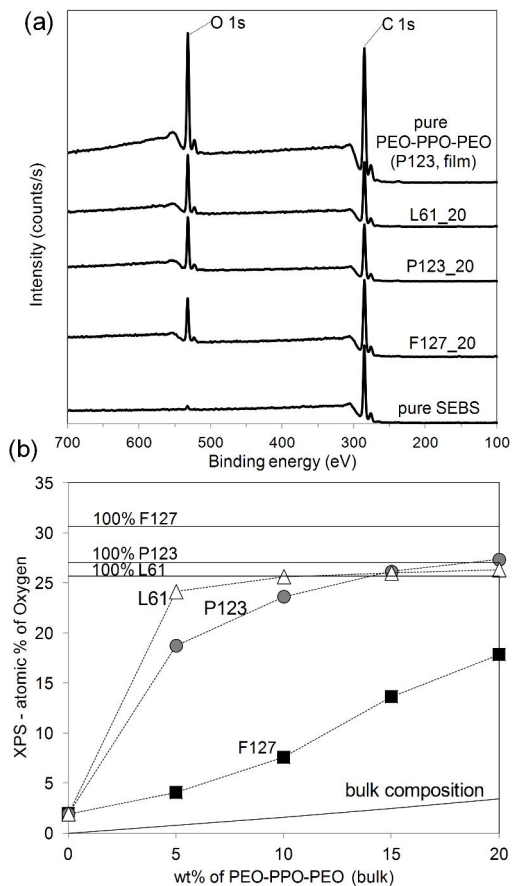
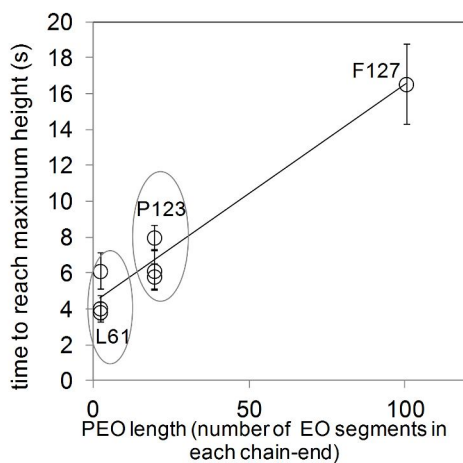


Figure 5 – (a) X-ray photoelectron spectroscopy (XPS) survey spectra for pure SEBS, F127_20, P123_20, L61_20 and pure PEO-PPO-PEO; (b) XPS results of the atomic percentage of oxygen as a function of blend bulk composition. The straight lines are theoretical values based on the chemical structure of each molecule.

The results show that the amount of PEO-PPO-PEO needed to achieve surface coverage and the consequent changes in surface properties is smaller for the molecules with lower molecular weight. Surface hydrophilization depends on the extension of PEO chain ends of each molecule when the surface is in contact with water. The length of PEO chain ends of the three PEO-PPO-PEO molecules chosen for this study varies greatly: F127 (PEO₁₀₀-PPO₆₅-PEO₁₀₀) has

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3 approximately 100 EO units in each side of the molecule, while P123 (PEO₂₀-PPO₆₉-PEO₂₀) and
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5 L61 (PEO₂-PPO₃₀-PEO₂) have in average 20 and 2 units of EO in each PEO block,
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7 respectively³⁵. The blends F127_20 and P123_5 have similar chemical compositions, but
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9 remarkably different wicking behavior, which indicate that the shorter PEO chains are activated
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11 faster in P123. An analogous behavior is observed when comparing the blends with saturated
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13 surfaces. The compositions with L61 molecules showed a faster wicking than the membranes
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15 containing P123 molecules (Figure 3). A plot of the time to reach the maximum height in the
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17 wicking experiments as a function of PEO length in each chain end (Figure 6) shows that
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19 wicking rate increased with decreasing PEO length. Furthermore, for each molecule of F127
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21 with two PEO chain-ends, there are approximately two times more P123 molecules and six times
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23 more L61 molecules, considering the same mass of polymer used.
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48 Figure 6 – Wicking results as a function of the number of EO segments in each side of the PEO-
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50 PPO-PEO molecules.
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3 Besides the idea of a longer time to extend and hydrophilize the surface, another possible
4 explanation is that the longer PEO chain-ends, like in F127, hindered the segregation of the
5 molecule. Both arguments are plausible when comparing F127_20 and P123_5, blends with
6 similar surface chemical composition and PPO-block length. The wicking rate was higher for
7 P123_5, indicating faster activation, but the amount of PEO-PPO-PEO (bulk composition) in this
8 blend is much smaller than in F127_20, indicating faster segregation.
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17 Results above showed that SEBS electrospun fibers blended with PEO-PPO-PEO molecules
18 presented graded morphology with a PEO-PPO-PEO-rich surface, resulting in mat
19 hydrophilization. Smaller PEO-PPO-PEO molecules seem to be more effective to generate faster
20 water absorption even though the order of molecular hydrophilicity (proportion of PEO) is
21 F127>P123>L61.
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29 Once the surface is saturated, the compositions with higher concentrations will tend to have a
30 thicker surface layer of PEO-PPO-PEO, which can contribute to fast interaction with water. But
31 this thicker layer can also be more easily removed or leached by water. In the particular case of
32 SEBS/L61 fibers, a liquid residue was observed whenever the mats were placed on a glass slide.
33 Leaching of L61_20 fibers by water was then observed by optical microscopy (Figure 7a). When
34 the flow of water passed (arrow in Figure 7a), L61 molecules were removed from the fibers
35 surface and formed bubbles in fractions of a second. The wetting behavior of the SEBS/L61
36 blends with higher concentrations of L61 was mainly a result of a liquid surface exuded from the
37 SEBS matrix. The SEM image of the L61_20 fibers (Figure 7b) also revealed a residue on the
38 substrate after fiber deposition, in addition to broken fibers. Higher concentrations of the smaller
39 molecules of L61 reduced the stability of the jet during electrospinning, leading to fiber breakage
40 in some points due to the electrical forces and bending instabilities.
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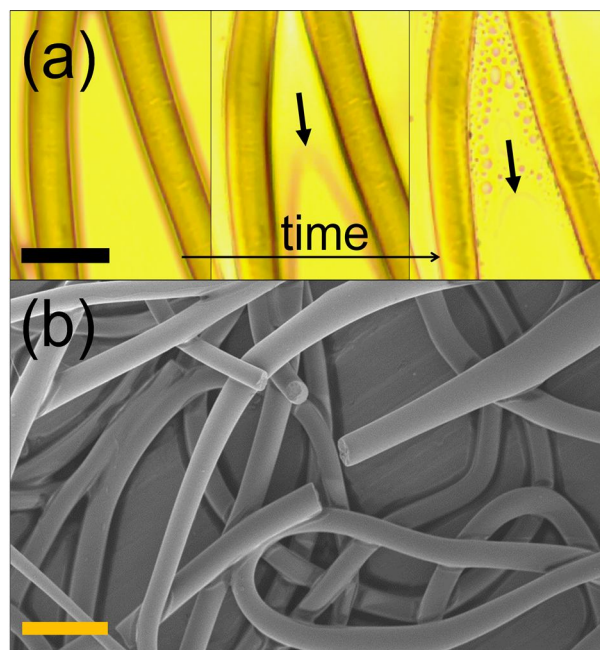


Figure 7 – L61_20 fibers: (a) L61 leaching observed by optical microscopy, in which the arrows indicate the water front advancing direction (scale bar = 10 μm); (b) SEM image of the same composition showing broken fibers (scale bar = 30 μm).

Leaching could not be observed for the other compositions with only optical microscopy and static contact angle measurements. Leaching is a problem for applications that demand long-term hydrophilicity, but it can be interesting for other applications where the release of molecules is targeted. A more systematic and detailed study is needed to understand how to control a specific leaching behavior of PEO-PPO-PEO molecules for a given application.

CONCLUSIONS

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3 Electrospun SEBS fibers were successfully hydrophilized by solution blending with
4 amphiphilic PEO-PPO-PEO molecules. During electrospinning and until solvent evaporation
5 these molecules segregated to the surface and completely altered the wetting behavior of the
6 mats. This was confirmed by the chemical composition at the very top surface.
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12 Although superhydrophilic considering only contact angle measurements, a drastic difference
13 in absorption time was noticed. Wicking tests quantified this difference revealing that the PEO-
14 PPO-PEO molecules with smaller molecular weight were more effective, enabling
15 hydrophilization with smaller amount of material incorporated in the SEBS matrix. Moreover,
16 smaller PEO chain-ends seemed to respond more rapidly when in contact with water, resulting in
17 faster wicking. High-speed imaging also reinforced the results.
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27 Liquid PEO-PPO-PEO (L61) is clearly leached from the fibers surface when in contact with
28 water, while the other types of PEO-PPO-PEO molecules (P123 and F127) seemed to produce
29 more robust hydrophilization.
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37 ACKNOWLEDGMENTS

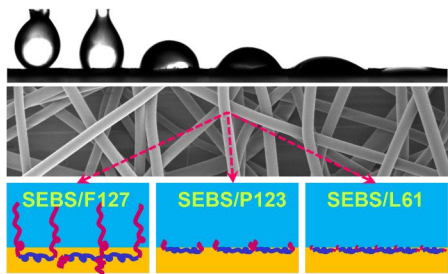
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42 financial support and Navid Sharifi and Professor Ali Dolatabadi from Concordia University for
43 the help with high-speed imaging.
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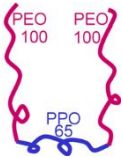


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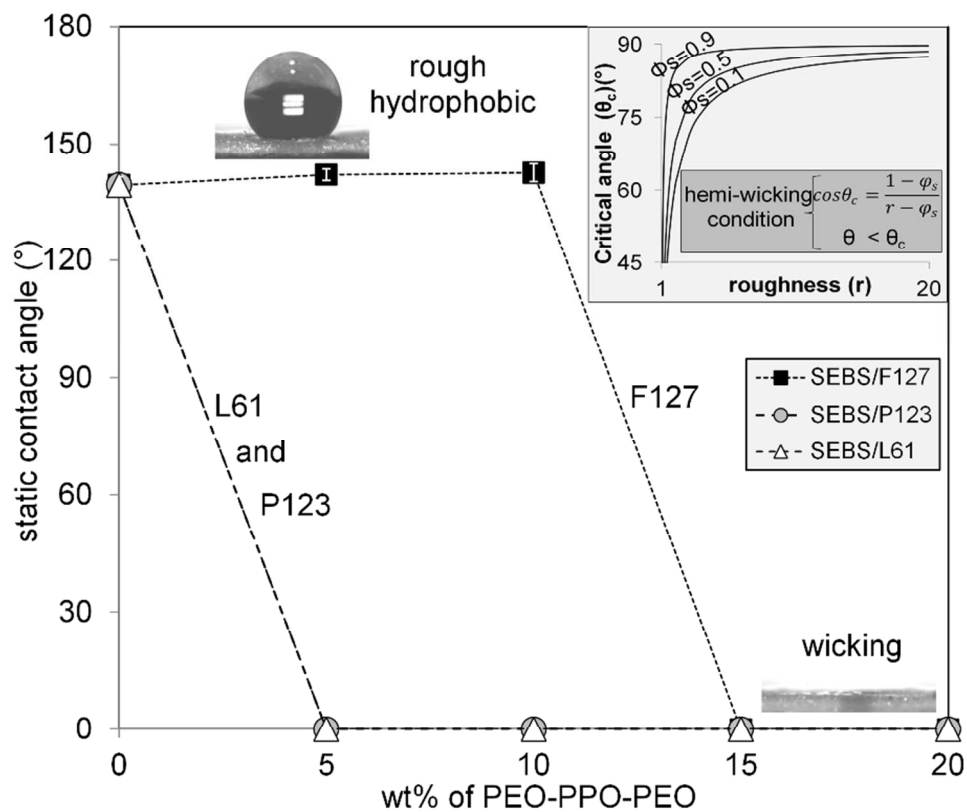
Table of Contents Graphic



1
2
3
4
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Polymer	F127	P123	L61
Molecular weight (g/mol)	12 600	5 800	2 000
wt% of PEO	73.2	30.0	10.0
Physical form	Flakes	Paste	Liquid
Comparative sketch			



36 Figure 1 – Water contact angle results for all electrospun mats as a function of PEO-PPO-PEO content. The
 37 insert is a plot of the hemi-wicking condition²⁰, the critical contact angle θ_c as a function of roughness r for
 38 different values of solid/liquid interface fraction (ϕ_s).
 39 80x69mm (300 x 300 DPI)

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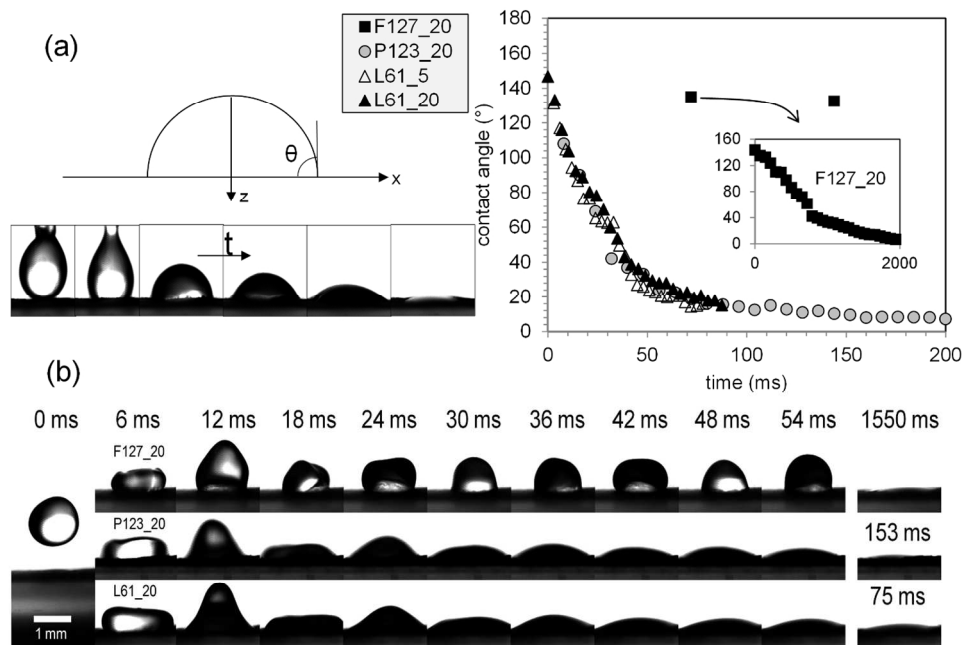


Figure 2 – (a) spreading and imbibition experiments methodology and results for the contact angle θ as a function of time; (b) drop impact images showing the last frame before impact as the first image and the total time for absorption as the final image for F127_20, P123_20 and L61_20 (top to bottom).
127x85mm (300 x 300 DPI)

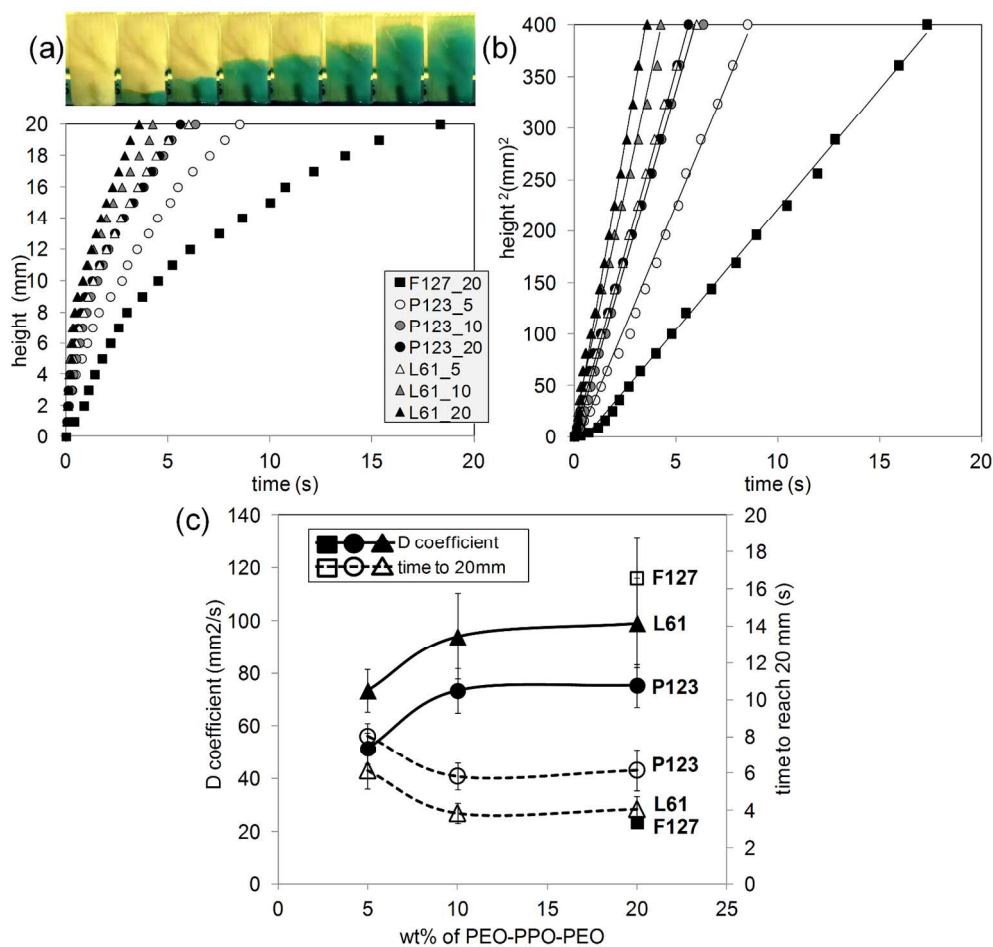


Figure 3 – Results for the wicking measurements: (a) example of the experiments pictures and the results for height as a function of time; (b) the square of height (h^2) versus time; (c) Diffusion coefficient D and total time to reach the maximum height as a function of PEO-PPO-PEO content.
150x143mm (300 x 300 DPI)

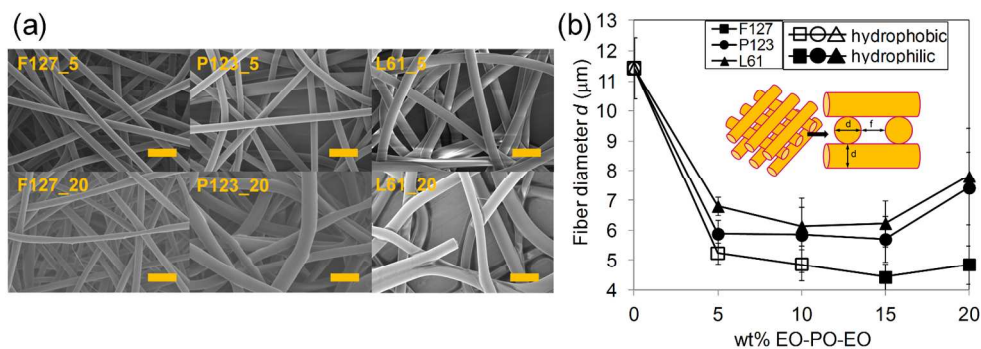


Figure 4 – (a) SEM micrographs of the samples containing 5 and 20 wt% of PEO-PPO-PEO (scale bar = 20 μm) and (b) the results of fiber diameter as a function of PEO-PPO-PEO content for all samples. 148x52mm (300 x 300 DPI)

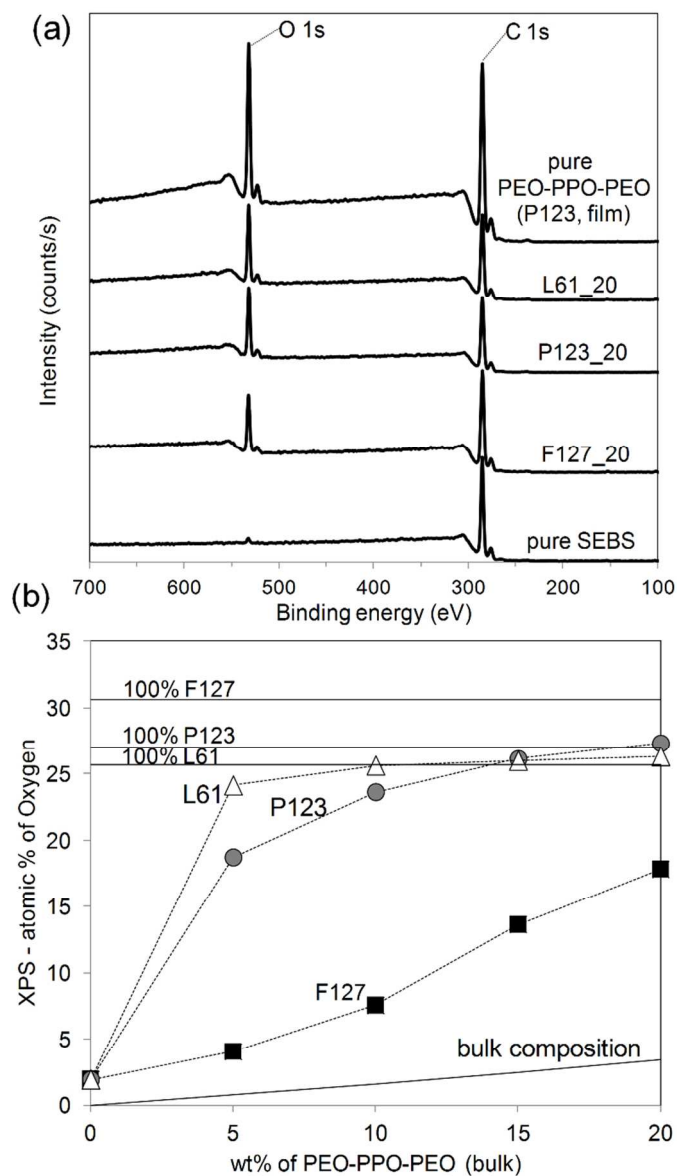


Figure 5 – (a) X-ray photoelectron spectroscopy (XPS) survey spectra for pure SEBS, F127_20, P123_20, L61_20 and pure PEO-PPO-PEO; (b) XPS results of the atomic percentage of oxygen as a function of blend bulk composition. The straight lines are theoretical values based on the chemical structure of each molecule. 70x119mm (300 x 300 DPI)

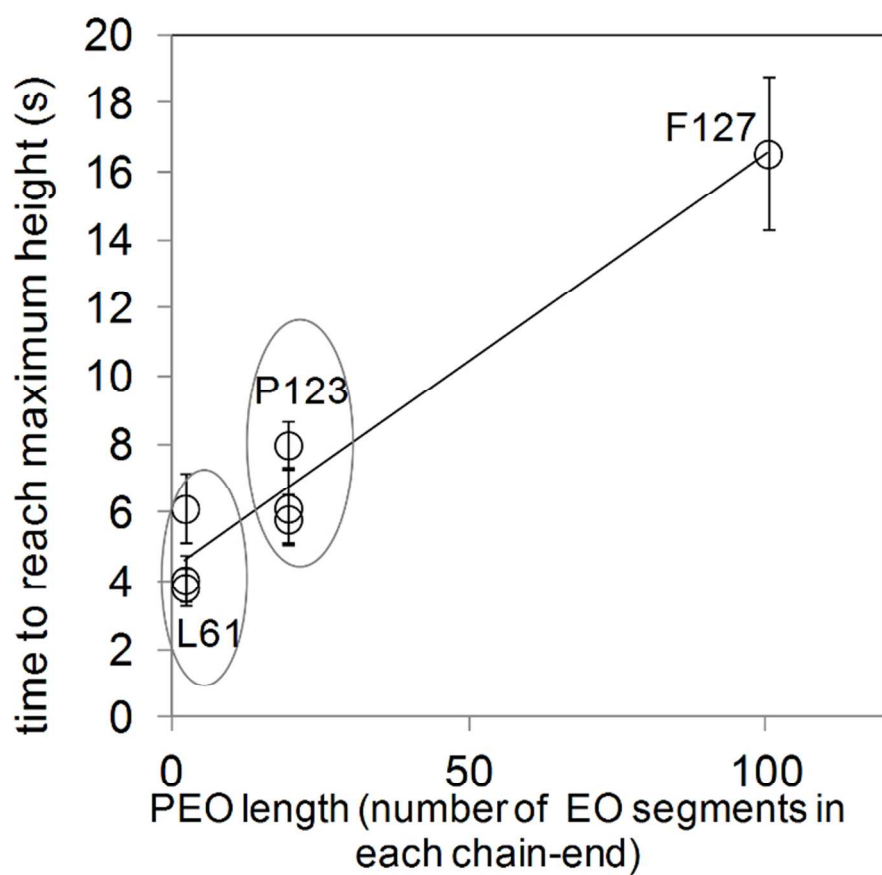


Figure 6 – Wicking results as a function of the number of EO segments in each side of the PEO-PPO-PEO molecules.
69x61mm (300 x 300 DPI)

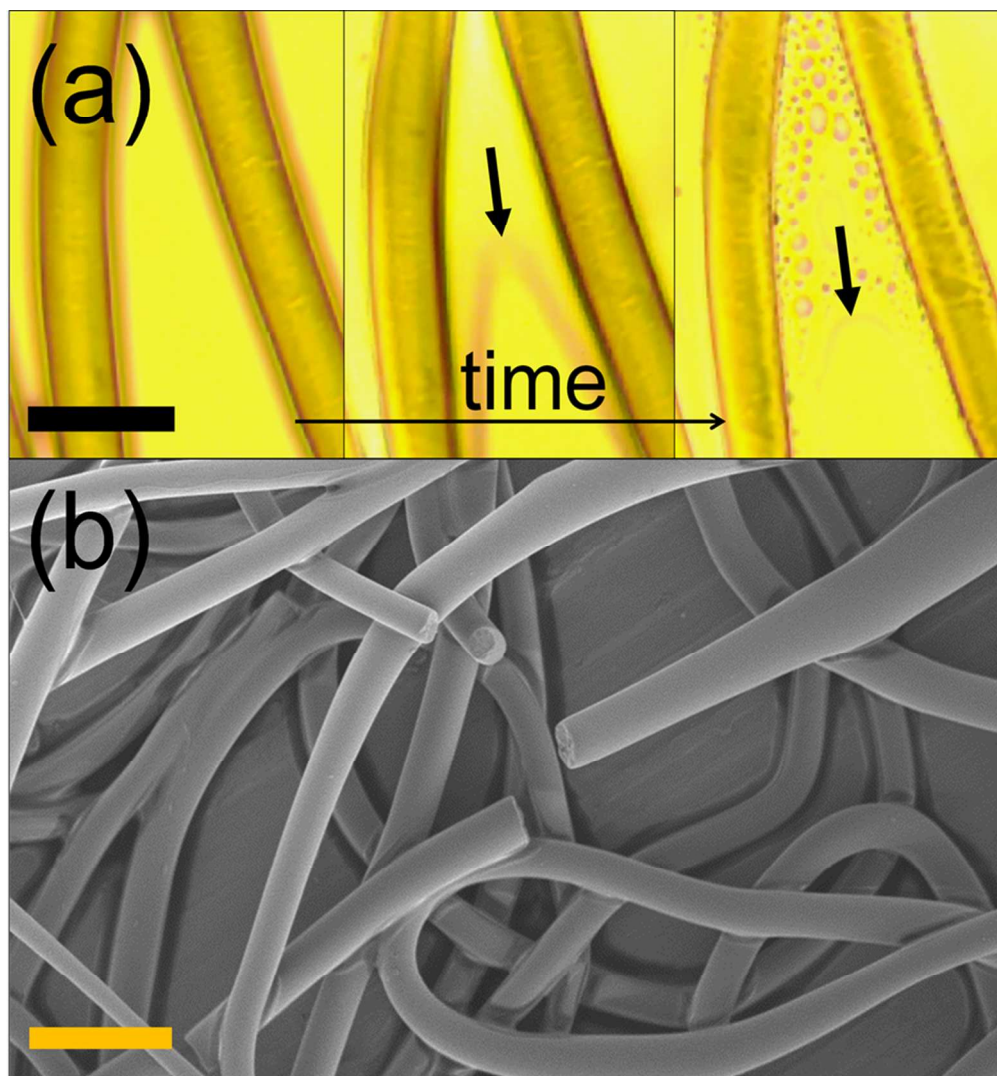


Figure 7 – L61_20 fibers: (a) L61 leaching observed by optical microscopy, in which the arrows indicate the water front advancing direction (scale bar = 10 μm); (b) SEM image of the same composition showing broken fibers (scale bar = 30 μm).
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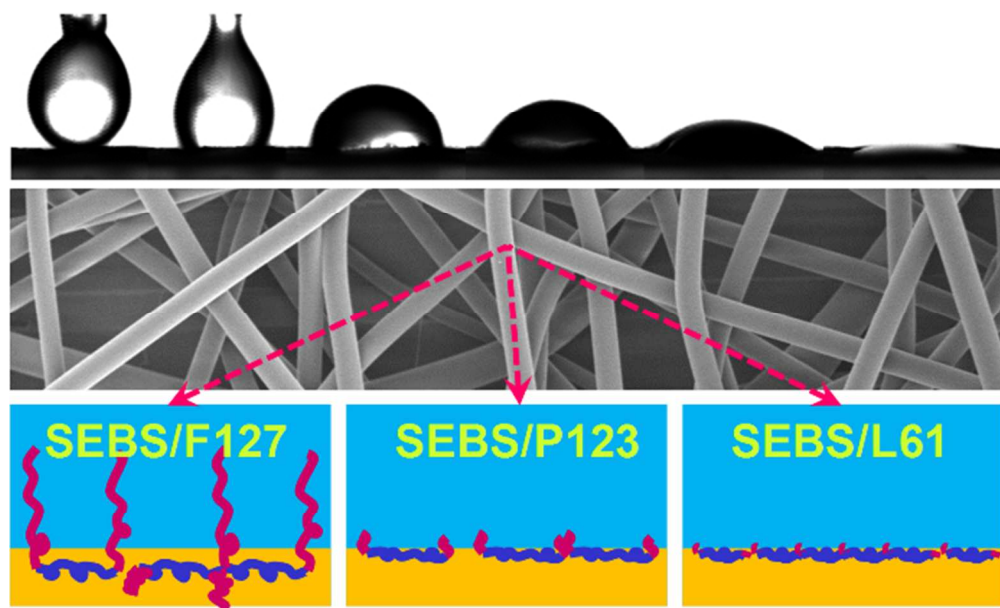


Table of contents graphic
58x35mm (300 x 300 DPI)